



# CS F211: DATA STRUCTURES & ALGORITHMS (2<sup>ND</sup> SEMESTER 2024-25) HASH MAPS, BINARY SEARCH TREES

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# MAP ABSTRACT DATA TYPE (ADT)

## What is a Map?

A Map is an abstract data type (ADT)

- stores key-value (k, v) pairs
- can you have duplicate keys? ✓

Let's say you want to implement a language dictionary.

Options: Vectors, LL, BST, Maps ✓

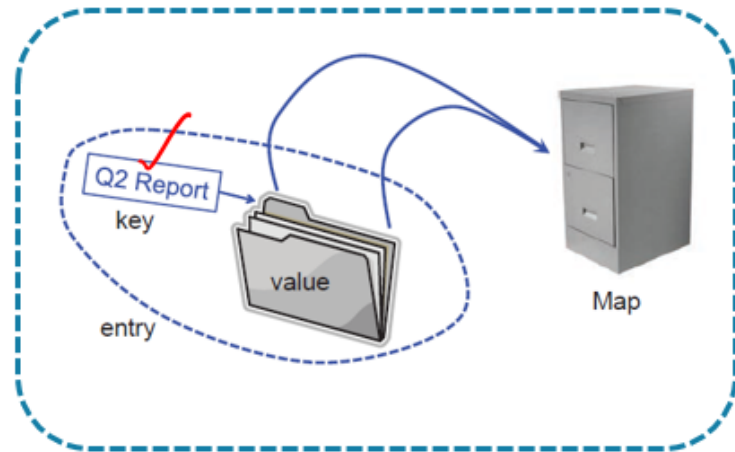
Associative store or Associative container: Maps

Operation	Output	Map
empty()	true	$\emptyset$
put(5, A)	$p_1 : [(5, A)]$	$\{(5, A)\}$
put(7, B)	$p_2 : [(7, B)]$	$\{(5, A), (7, B)\}$
put(2, C)	$p_3 : [(2, C)]$	$\{(5, A), (7, B), (2, C)\}$
put(2, E)	$p_3 : [(2, E)]$	$\{(5, A), (7, B), (2, E)\}$
find(7)	$p_2 : [(7, B)]$	$\{(5, A), (7, B), (2, E)\}$
find(4)	end	
find(2)	$p_3 : [(2, E)]$	
size()	3	
erase(5)	-	$\{(7, B), (2, E)\}$
erase( $p_3$ )	-	$\{(7, B)\}$
find(2)	end	

```

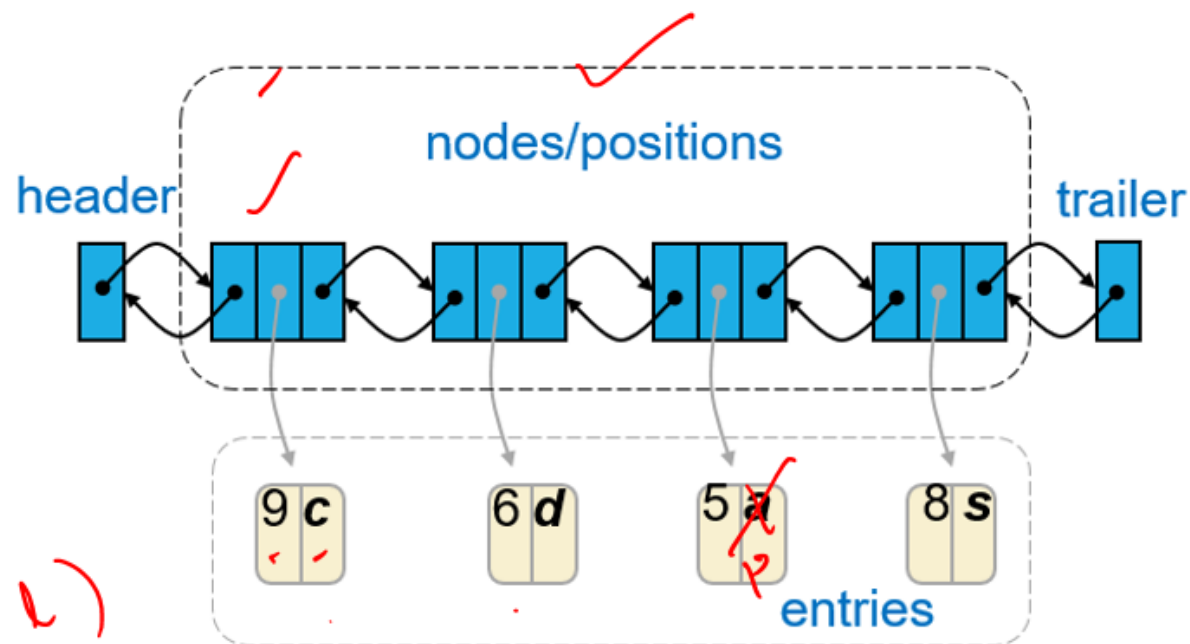
1 #include <bits/stdc++.h>
2 using namespace std;
3
4 int main()
5 {
6     priority_queue<int> pq;
7     pq.push(90);
8     pq.push(30);
9     pq.push(90);
10    cout << pq.top() << " ";
11    pq.pop();
12    cout << pq.top() << " ";
13    pq.pop();
14    return 0;
15 }

```



Does a priority queue allow duplicate keys?

# IMPLEMENTATION OF MAPS



(using an unsorted list)

```
Algorithm put (k, v) {  
  for each p in (S.begin(), S.end()) do  
    if (p->key() == k) then  
      p->keyValue(v);  
      return p;  
  p=S.insertBack ((k,v)) //no entry with key as 'k'  
  n=n+1;  
  return p;  
}
```

```
Algorithm erase(k){  
  for each p in (S.begin(), S.end()) do  
    if (p->key() == k) then  
      S.erase(p);  
      n = n - 1;  
}
```

```
1 #include <iostream>
2 #include <string>
3 #include <map>
4
5 using namespace std;
6 int main() {
7
8     map < string, int> Students;
9
10    Students.insert(std::pair<string, int>("Tushar", 91));
11
12    Students.insert(std::pair<string, int>("Akshat", 94));
13
14    Students.insert(std::pair<string, int>("Geet", 86));
15
16    cout << "Map size is: " << Students.size() << endl;
17
18    cout << endl << "Default map Order is: " << endl;
19
20    for (map<string, int>::iterator it = Students.begin();
21         it != Students.end(); ++it) {
22
23        cout << (*it).first << ": " << (*it).second << endl;
24    }
25 }
```

Implementation: ? B.S.T

R.B.T

Map size is: 3  
Default map Order is:  
Akshat: 94  
Geet: 86  
Tushar: 91

Search complexity: ?

Insertion/Deletion: ?

Yes + Redundant

```
1 #include <iostream>
2 #include <unordered_map>
3 using namespace std;
4
5 int main()
6 {
7
8     unordered_map<string, int> mymap;
9
10    // inserting values by using [] operator
11    mymap["Rajesh"] = 10;
12    mymap["Akash"] = 20;
13    mymap["Shyamala"] = 30;
14    mymap["Radhika"] = 30;
15    mymap["Rohit"] = 30;
16    mymap["Sachin"] = 30;
17
18    // Traversing an unordered map
19    for (auto x : mymap)
20        cout << x.first << " " << x.second << endl;
21 }
```

Implementation: ?

Hash Table

Sachin 30  
Rohit 30  
Shyamala 30  
Radhika 30  
Akash 20  
Rajesh 10

Search complexity: ?

Insertion/Deletion: ?

$O(1)$

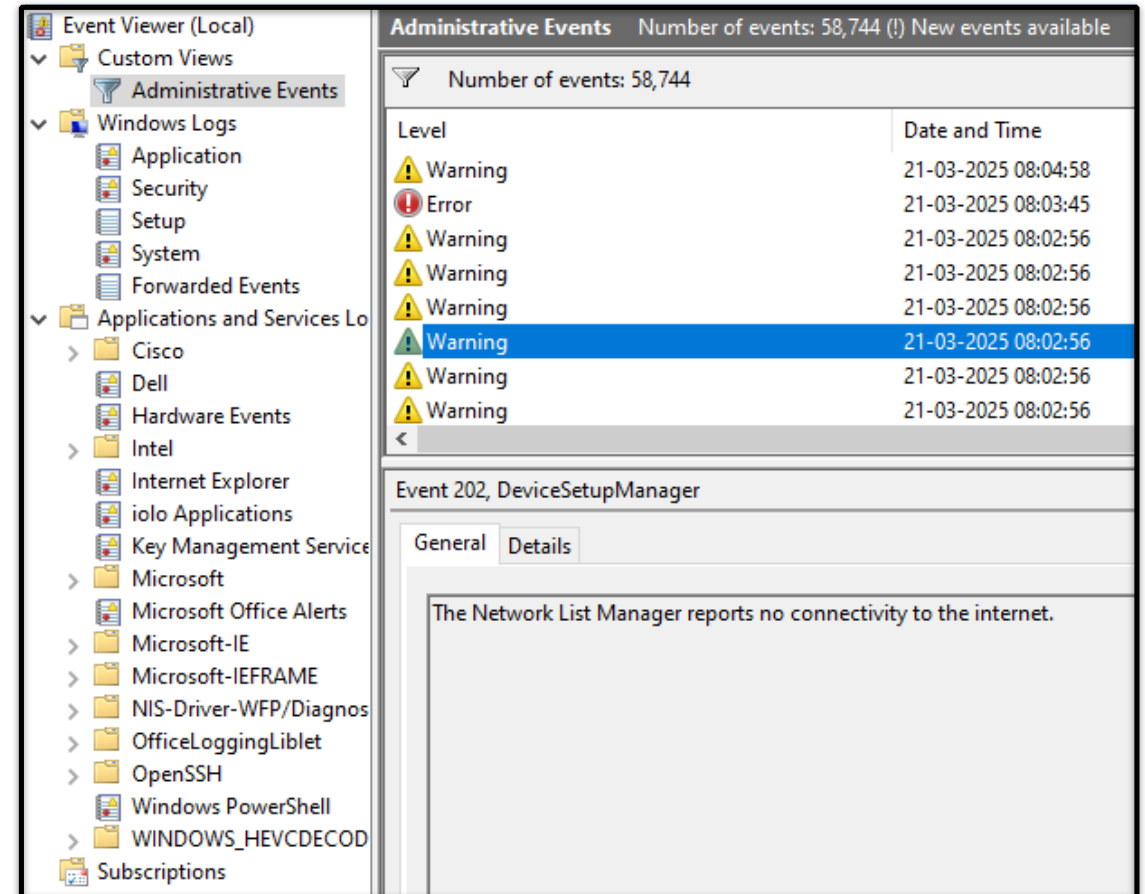
# DICTIONARY ABSTRACT DATA TYPE (ADT)

-Like a map, a **dictionary** stores key-value pairs (k, v) called as entries.

-When a map insists that entries have unique keys, a dictionary allows for multiple entries to have the **same key**.

- Example: **park**: noun, and verb

Operation	Output	Dictionary
put(5, A)	p1:(5, A)	{{(5, A)}
put(7, B)	p2:(7, B)	{{(5, A), (7, B)}
put(2, C)	p3:(2, C)	{{(5, A), (7, B), (2, C)}
put(8, D)	p4:(8, D)	{{(5, A), (7, B), (2, C), (8, D)}
put(2, E)	p5:(2, E)	{{(5, A), (7, B), (2, C), (8, D), (2, E)}
find(7)	p2:(7, B)	{{(5, A), (7, B), (2, C), (8, D), (2, E)}
findAll(2)	{p3, p5}	{{(5, A), (7, B), (2, C), (8, D), (2, E)}
erase(5)	—	{{(7, B), (2, C), (8, D), (2, E)}



(Ex: A log-file or audit trail using unsorted sequence)



# HASH TABLE (HASH MAP) DATA STRUCTURE

What is a Hash Table or Hash Map?

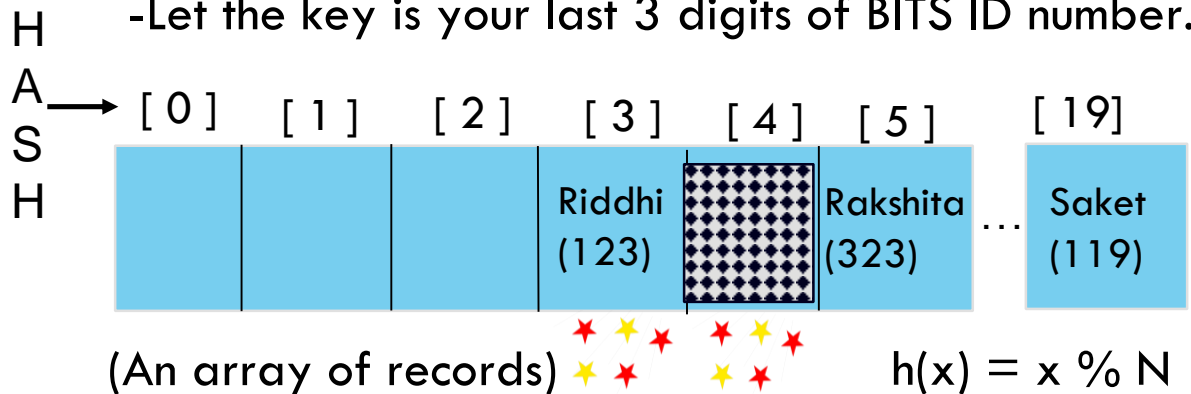
-A data structure used to implement the Map ADT

What are keys and values here?

-The simplest kind of hash table is an array of records.

-Let us consider an example that has 20 records.

-Let the key is your last 3 digits of BITS ID number.

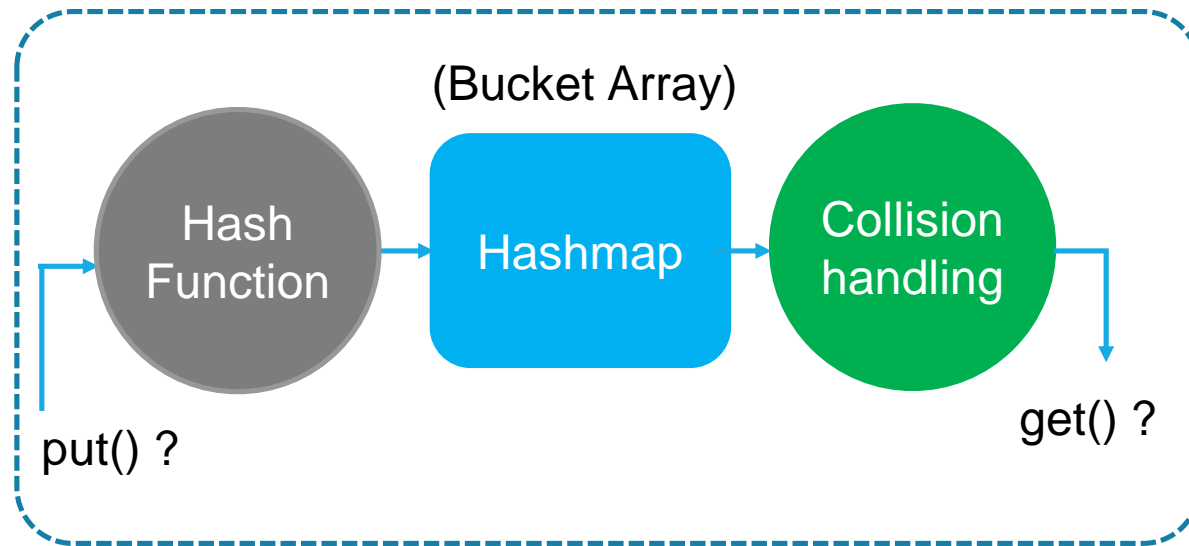


Rakshita with 323 will go where?

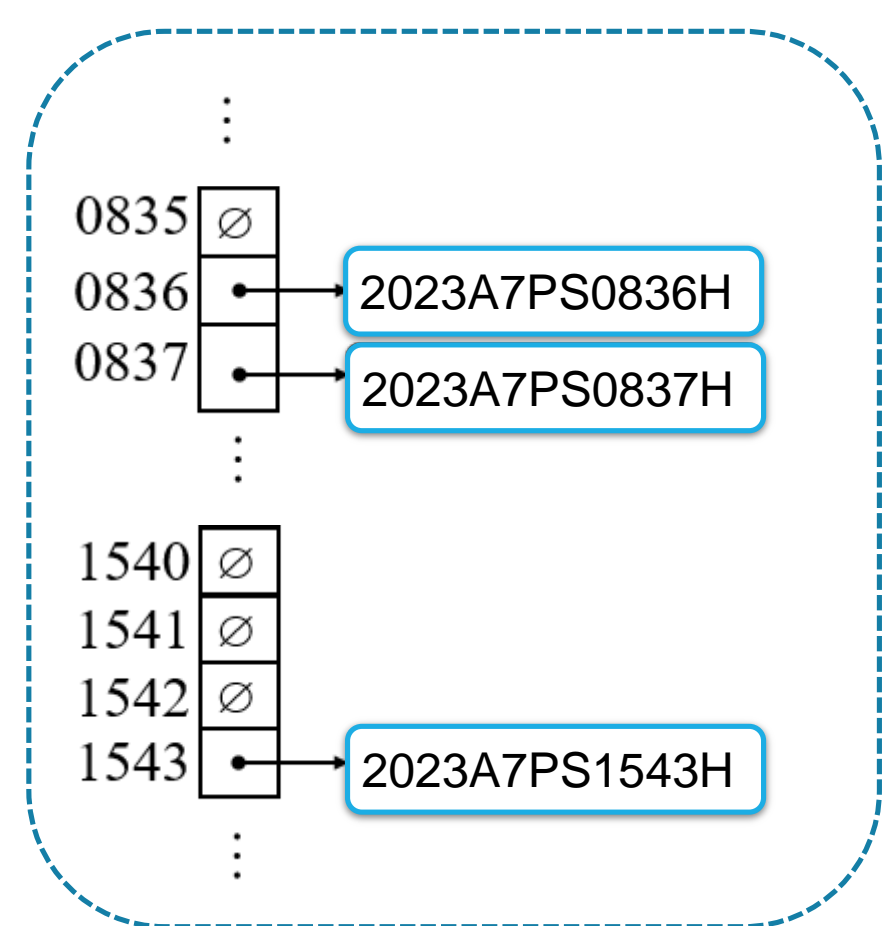


(Ex: Pigeonhole cabinet or Storage lockers at CSE dept)

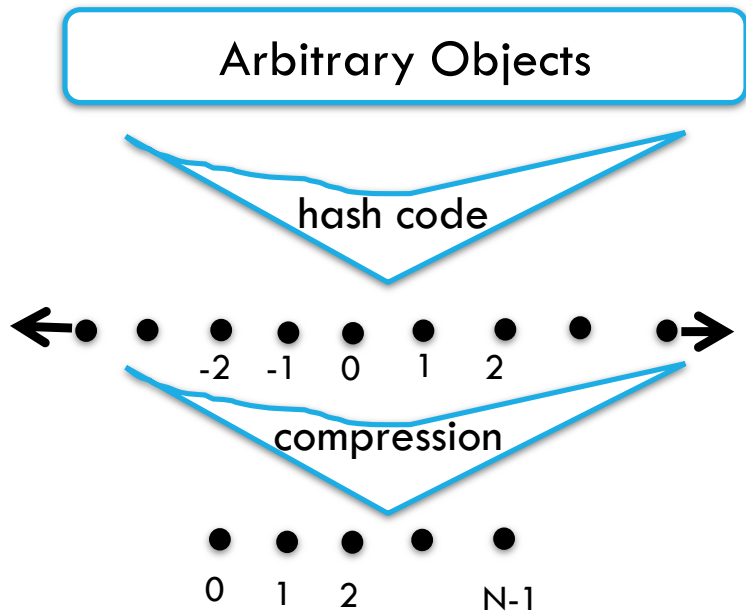
# KEY COMPONENTS OF HASH MAP



**Applications:** Indexing in Oracle, and MySQL; Browser Cache (Chrome, Firefox); Grammarly (n-gram hashing); Google maps (Key: location ID, Values: neighbors, costs on links); Symbol Table (Lexical analyzers and Parsers in Compilers), Distributed Hash Tables (BitTorrent), etc...



# HASH FUNCTIONS: CHARACTERISTICS



Common Techniques for Computing Hash codes:

- Integer cast, component sum, polynomial hash codes, cyclic shift hash codes.  $H("ab")=0x6162 = 24,930$   $H("cat")=99('c')+97('a')+116('t')=312$

Hash codes to indices in Hash table:  $H("hi")=(104('h')\times 31^1 + 105('i')\times 31^0) \% 1000$

- Division:**  $index = h(k) \bmod M$ , where M is table size(Prime no.)
- Multiply-Add-Divide (MAD):**  $index = (a \cdot h(k) + b) \bmod M$

```
hash<string> hashFunc;
```

```
size_t hashCode = hashFunc(text);
```

Hash Code of "Hello": 15954192381400062680

```
string text = "Hello";
```

```
string hashValue = sha256(text);
```

(Hash value of Hello)



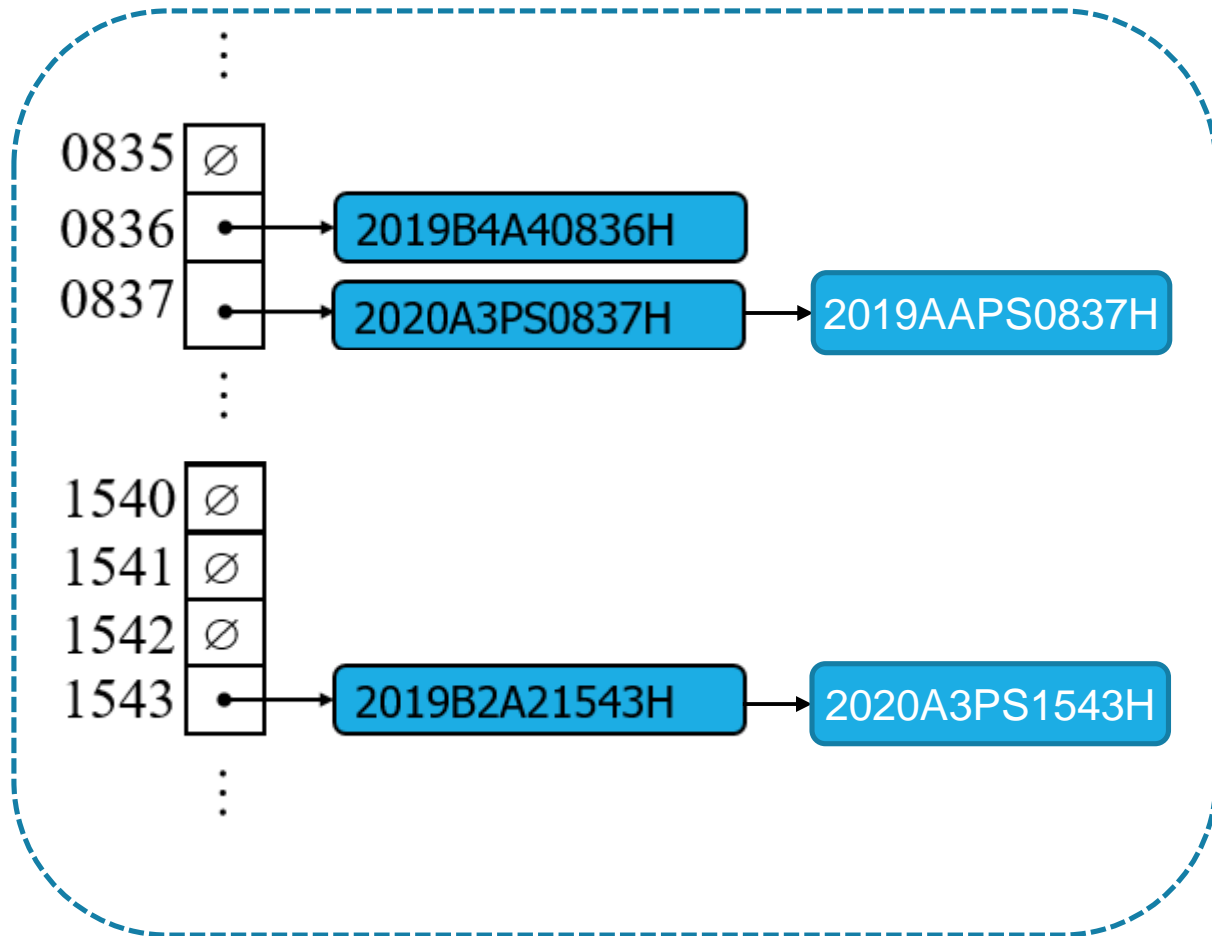
185f8db32271fe25f561a6fc938b2e264306ec304eda518007d1764826381969

**Easy to compute:** It should be easy to compute. **Uniform distribution:** It should provide a uniform distribution across the hash table and should not result in clustering. **Less collisions:** Collisions occur when pairs of elements are mapped to the same hash value. These should be avoided.

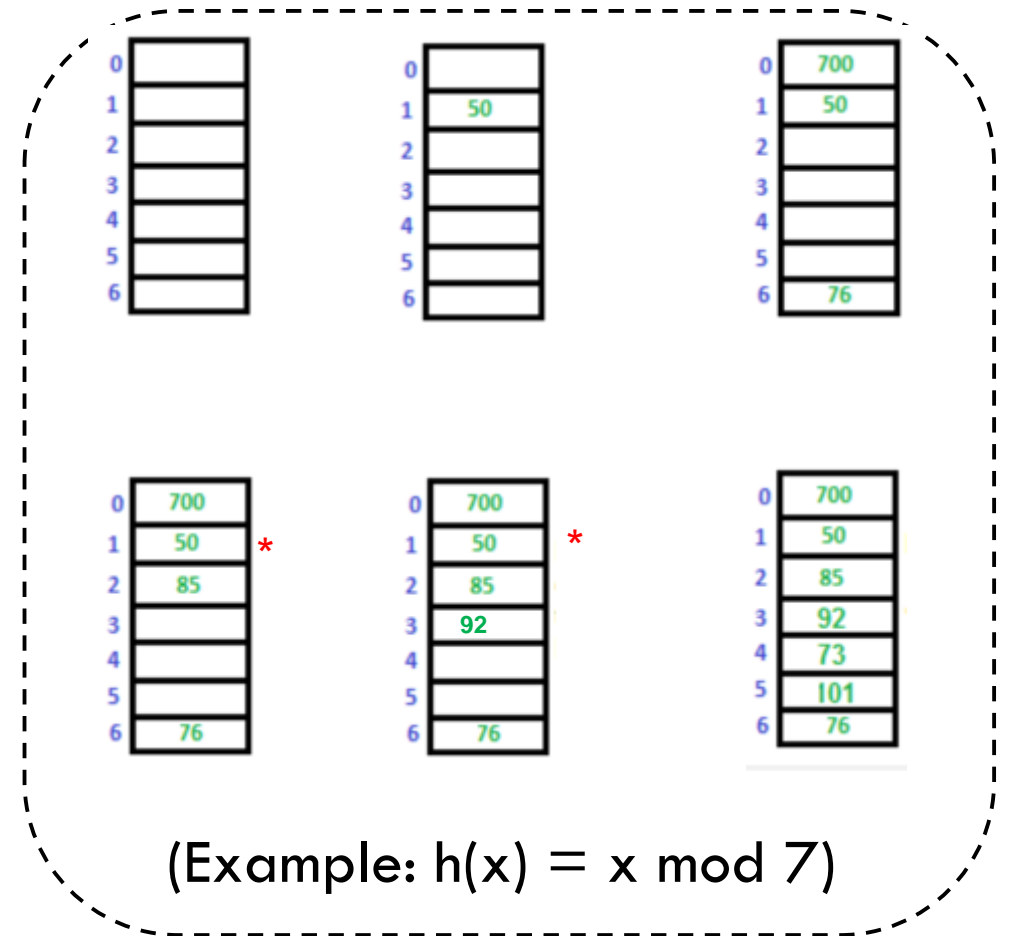
perform a cyclic left shift by 5 bits, then XOR with the byte



# COLLISION HANDLING TECHNIQUES

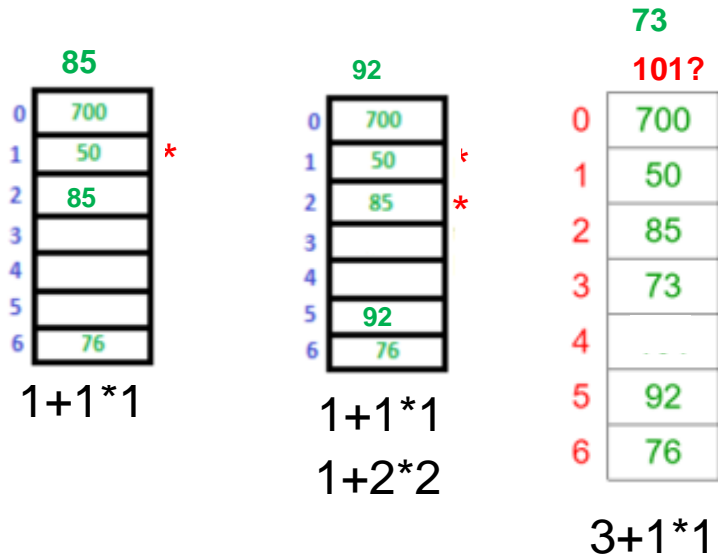
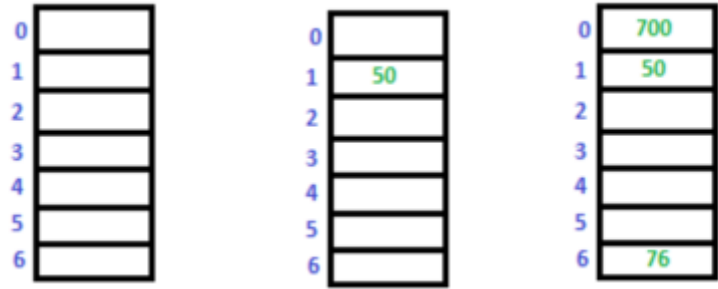


(Open Hashing: Separate Chaining)



(Example:  $h(x) = x \bmod 7$ )

(Closed Hashing: Linear Probing)

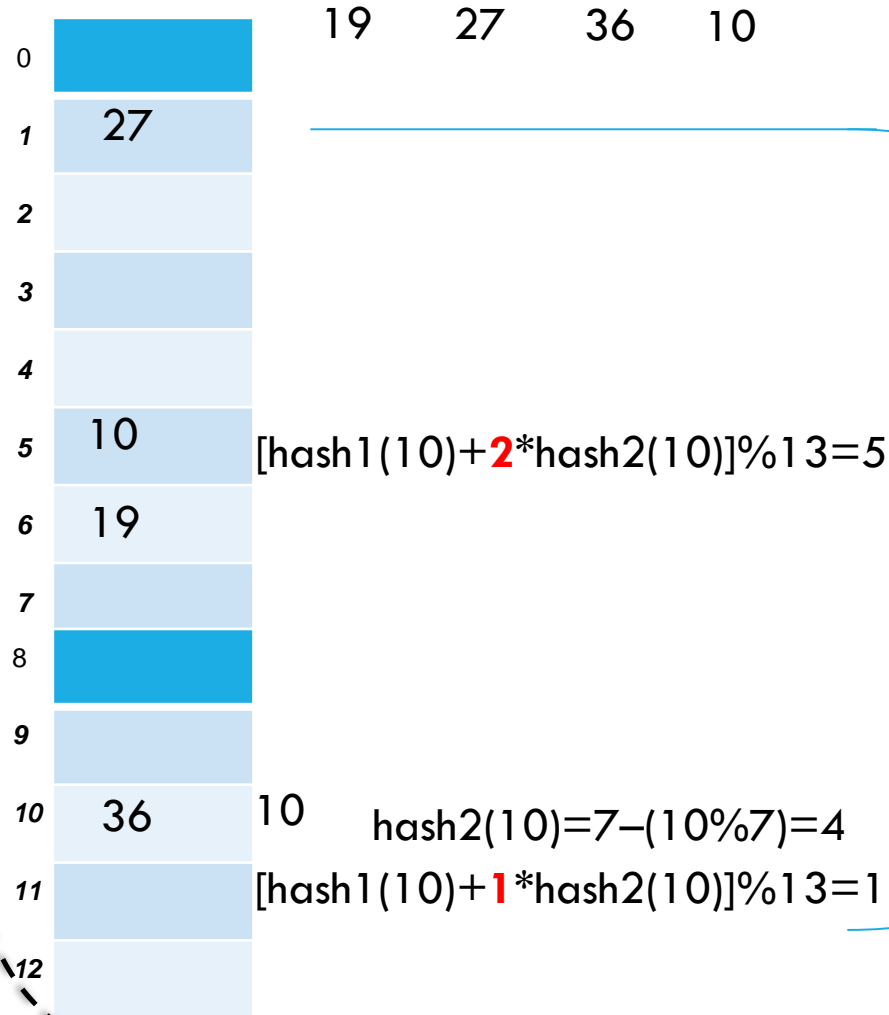


[Ex:  $h'(x) = x \text{ mod } 7$ ]

$h(x) = (h'(x) + i^2) \text{ mod } 7$

(Closed Hashing: Quadratic Probing)

An Example:  $\text{hash1}(\text{key}) = \text{key} \% 13$ ,  $\text{hash2}(\text{key}) = 7 - (\text{key} \% 7)$



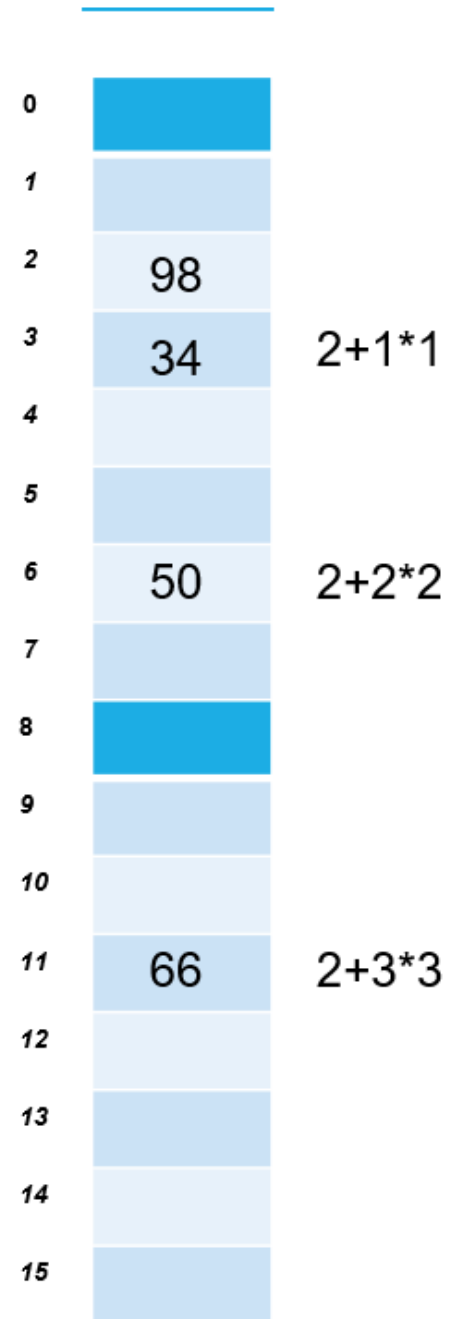
(Double Hashing)

# HOW IMPORTANT IS TABLE SIZE?

- Linear probing will **always** find an open spot if one **exists** (It might be a long search but we will find it).
- However, this is not the case with quadratic probing unless you take care in selecting the **table size** correctly.
- 98, 34, 50, 66, 82
- $h'(x) = x \bmod 16$

$82 \bmod 16 = 2$  → does not get inserted as  $(2 + 4 * 4) \bmod 16 = 2$  which is full.

Hence, in order to guarantee that your quadratic probes will hit every single available spot eventually, your **table size** must meet these requirements: - a prime number, - never be  $>$  half full, -  $> 1.3$



# IMPLEMENTATION OF HASH MAP

```
#include <iostream> #include <vector>
#include <list> #include <string>
using namespace std;
class HashMap { //Hash Table Class
private:
    static const int TABLE_SIZE = 10;
    vector<list<pair<string, int>>> table;
    int hashFunction(const string &key) {
        hash<string> hashFunc;
        return hashFunc(key) % TABLE_SIZE;
    }
public:
    HashMap() {
        table.resize(TABLE_SIZE);
    }
    void insert(const string &key, int value) {
        int index = hashFunction(key);
        // Check if key already exists, update it
        for (auto &p : table[index]) {
            if (p.first == key) {
                p.second = value;
                return;
            }
        }
        // If key not found, insert new key-value
        table[index].emplace_back(key, value);
    }
};
```

```
void remove(const string &key) {
    int index = hashFunction(key);
    auto &chain = table[index];
    for(auto it=chain.begin(); it!=chain.end(); ++it){
        if (it->first == key) {
            chain.erase(it);
            return;
        }
    }
    cout << key << " not found.";
}
int search(const string &key) {
    int index = hashFunction(key);
    for (auto &p : table[index]) {
        if (p.first == key)
            return p.second;
    }
    throw runtime_error("Key not found");
}
void display() {
    for (int i = 0; i < TABLE_SIZE; i++) {
        cout << "Index " << i << ": ";
        for (auto &p : table[i])
            cout << p.first << p.second;
        cout << endl;
    }
};
```

```
int main() {
    HashMap map;
    map.insert("Riddhi", 25);
    map.insert("Aryan", 30);
    map.insert("Mahadevan", 22);
    map.insert("Saket", 40);
    map.insert("Purva", 29);
    map.display();
    map.remove("Purva");
    map.display();
    return 0;
}
```

Lab 11 Next week

```
Index 0: [Mahadevan -> 22]
Index 1: [Riddhi -> 25]
Index 2: [Aryan -> 30]
Index 3: [Purva -> 29]
Index 4:
Index 5:
Index 6:
Index 7:
Index 8:
Index 9: [Saket -> 40]
Index 0: [Mahadevan -> 22]
Index 1: [Riddhi -> 25]
Index 2: [Aryan -> 30]
Index 3:
Index 4:
Index 5:
Index 6:
Index 7:
Index 8:
Index 9: [Saket -> 40]
```

# CACHING IMPLEMENTED USING HASH TABLES

```
class FileManager {
private:
    int cap, timer;
    HashMap<int> map;
    vector<CacheItem*> cache;
    int freeSpace() {
        int idx = 0;
        for (int i = 0; i < cap; i++) {
            if (cache[i]->lastUsedTime == -1) {
                cout << "Free space found at " << i << "\n";
                return i;
            }
            if(cache[i]->lastUsedTime < cache[idx]->lastUsedTime) idx = i;
        }
        cout << "No free space found, removing " << cache[idx]->name
                << " to clear index " << idx << "\n";
        map.remove(cache[idx]->name);
        return idx;
    }
};
```

Lab 11 Next week

```
Adding hello.txt ...
Free space found at 0
>> Hello World!

Adding bio.txt ...
Free space found at 1
>> My name is X

Adding lorem.txt ...
Free space found at 2
>> Lorem ipsum dolor sit amet, consectetur adipiscing elit

Fetching hello.txt ...
hello.txt found in cache at index 0
>> Hello World!

Adding sample.txt ...
No free space found, removing bio.txt to clear index 1
>> The quick brown fox jumps over the lazy dog

Fetching bio.txt ...
bio.txt not found in cache
No free space found, removing lorem.txt to clear index 2
>> My name is X
```



# DNS LOOKUP USING HASH MAPS

- Each DNS server keeps track of its immediate children servers using a hashmap.

```
C:\Users\C R Hota>nslookup td.bits-hyderabad.ac.in
Server: UnKnown
Address: 172.16.0.30

Non-authoritative answer:
Name: td.bits-hyderabad.ac.in
Address: 182.75.45.29

C:\Users\C R Hota>nslookup www.google.com
Server: UnKnown
Address: 172.16.0.30

Non-authoritative answer:
Name: www.google.com
Addresses: 2404:6800:4009:815::2004
           172.217.174.68

C:\Users\C R Hota>
```

```
Adding bits.pilani.hpc ...

Looking for .bits child server
Not found, creating .bits child server
Forwarding to .bits child server

Looking for .pilani child server
Not found, creating .pilani child server
Forwarding to .pilani child server

Looking for .hpc child server
Not found, creating .hpc child server
Forwarding to .hpc child server

Authoratative server reached, IP 192.222.115.111

Adding in.ka.bangalore.gov ...

Looking for .in child server
Not found, creating .in child server
Forwarding to .in child server
```

# IMPL. OF LINEAR PROBING & PERFORMANCE

```
void insert(const string &key, int value) {  
    int index = hashFunction(key);  
    int originalIndex = index;  
    bool found = false;  
    while (table[index].isOccupied && !table[index].isDeleted) {  
        if (table[index].key == key) { // Key exists, update value  
            table[index].value = value;  
            return;  
        }  
        index = (index + 1) % TABLE_SIZE;  
        if (index == originalIndex) { // Full table check  
            cout << "Hash table is full! Cannot insert.\n";  
            return;  
        }  
    }  
}
```



```
// Insert new key-value pair  
table[index].key = key;  
table[index].value = value;  
table[index].isOccupied = true;  
table[index].isDeleted = false;  
}
```

- In the worst case, searches, insertions and removals on a hash table take ? time.
- The worst case occurs when all the keys inserted into the map collide.
- The load factor  $\alpha = n/N$  affects the performance of a hash table. Default load factor is 0.75.

Rehashing




# ORDERED MAPS: FLIGHT DATABASE

In some applications, looking up values based on associated keys is **not enough**.

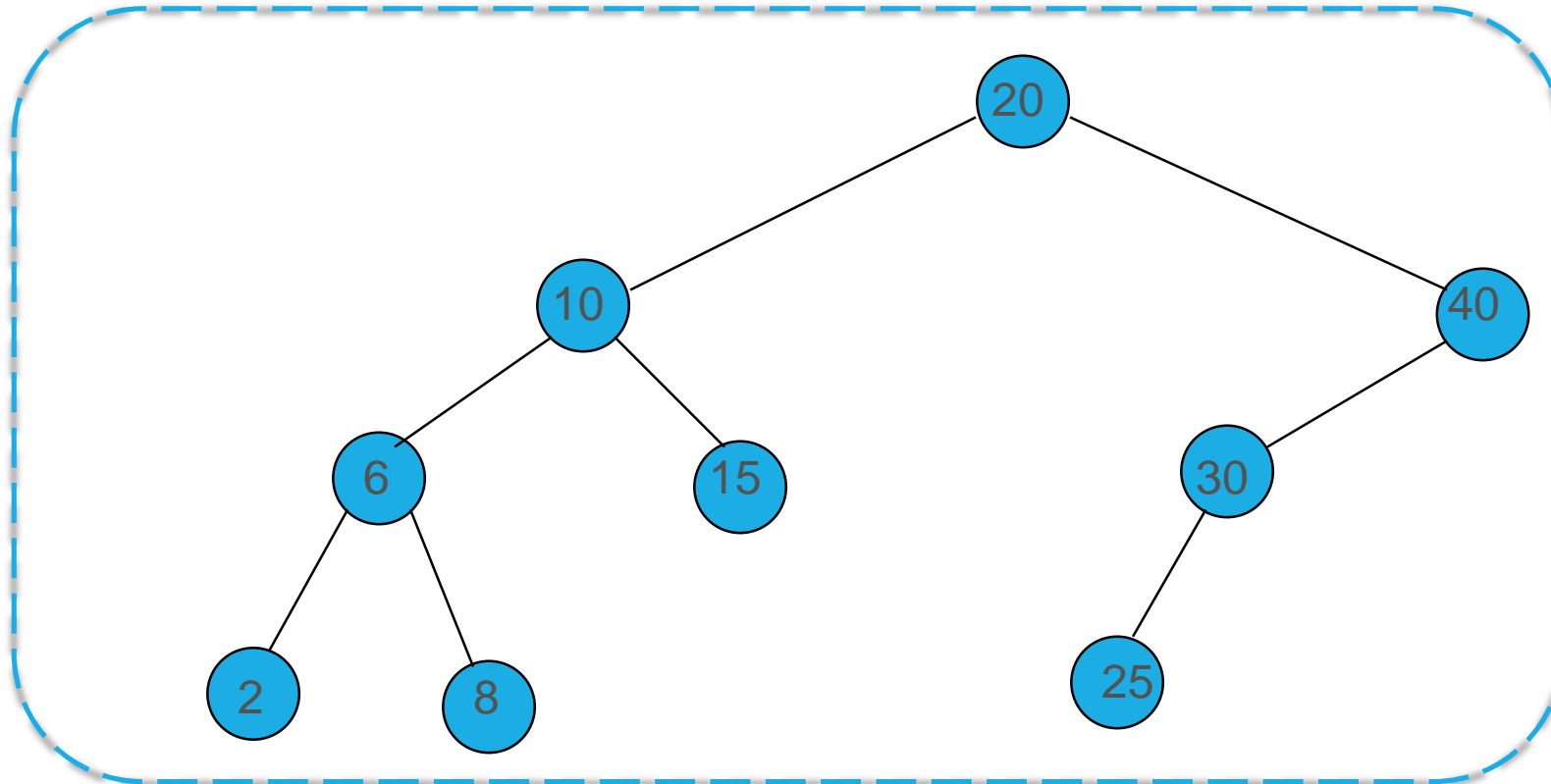
We often also want to keep the entries in a map **sorted** according to some total order and be able to look up keys and values based on this ordering. ([ORDERED MAP](#)).

Ex: Mid semester scores total display of CS F211.

Hashtables and lists are **not** the right ones, rather **Skip lists** and **BSTs**.

Flights from Hyderabad to New Delhi									
<	Thu, Apr 13 ₹ 5,637	Fri, Apr 14 ₹ 5,432	Sat, Apr 15 ₹ 5,645	Sun, Apr 16 ₹ 5,432	Mon, Apr 17 ₹ 5,432	Tue, Apr 18 ₹ 5,432	Wed, Apr 19 ₹ 5,432	Thu, Apr 20 ₹ 6,627	>
Sorted By:	Departure	Duration	Arrival	Price ↑					
<a href="#">Lock This Price</a>	 Go First G8 424	<b>04:30</b> Hyderabad	02 h 10 m Non stop	<b>06:40</b> New Delhi	<b>₹ 5,432</b>	<a href="#">VIEW PRICES</a>			
● Get Rs 700 off using MMTSUPER; get additional upto 10% off on SBI credit cards using code MMTSBI								<a href="#">View Flight Details</a>	
<a href="#">Lock This Price</a>	 IndiGo 6E 5605	<b>21:45</b> Hyderabad	02 h 20 m Non stop	<b>00:05</b> <sup>+1 DAY</sup> New Delhi	<b>₹ 5,437</b>	<a href="#">VIEW PRICES</a>			
● Get Rs 586 off using MMTSURPRISES; get additional upto 10% off on SBI credit cards using code MMTSBI								<a href="#">View Flight Details</a>	
<a href="#">Lock This Price</a>	 Vistara UK 870	<b>20:30</b> Hyderabad	02 h 15 m Non stop	<b>22:45</b> New Delhi	<b>₹ 5,636</b>	<a href="#">VIEW PRICES</a>			
● Get Rs 400 off using MMTBONUS; get additional upto 10% off on SBI credit cards using code MMTSBI									

# BINARY SEARCH TREE (BST) & ORDERED MAPS

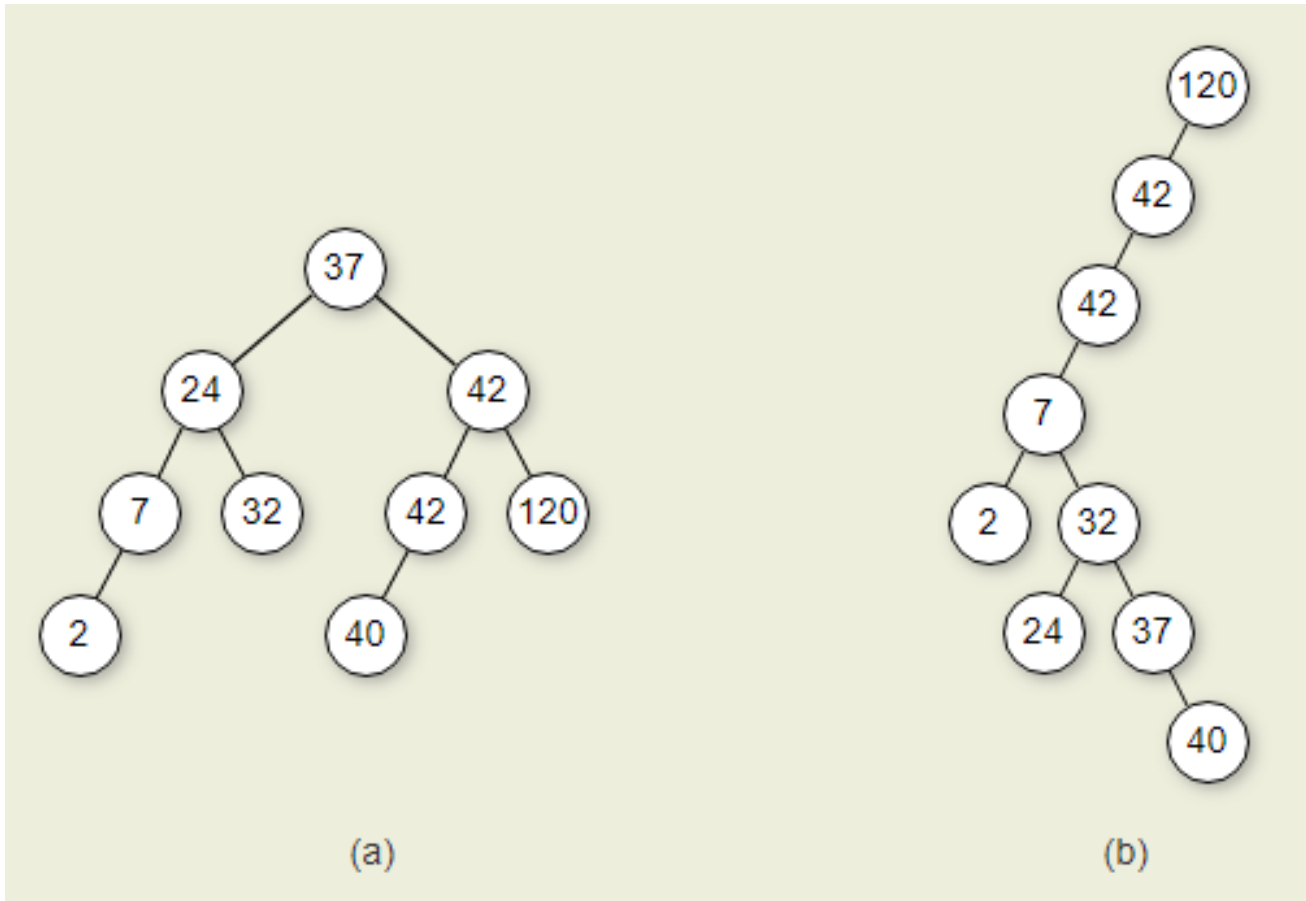


Keys are: 20, 10, 6, 2, 8, 15, 40, 30 and 25

To get an ascending order, what is needed?

If node with key 8 has a left child with key 3, what would be the type?

# ORDER OF INSERTION IS IMPORTANT



(a) if values are inserted in the order 37, 24, 42, 7, 2, 40, 42, 32, 120, (b) If the order is 120, 42, 42, 7, 2, 32, 37, 24, 40

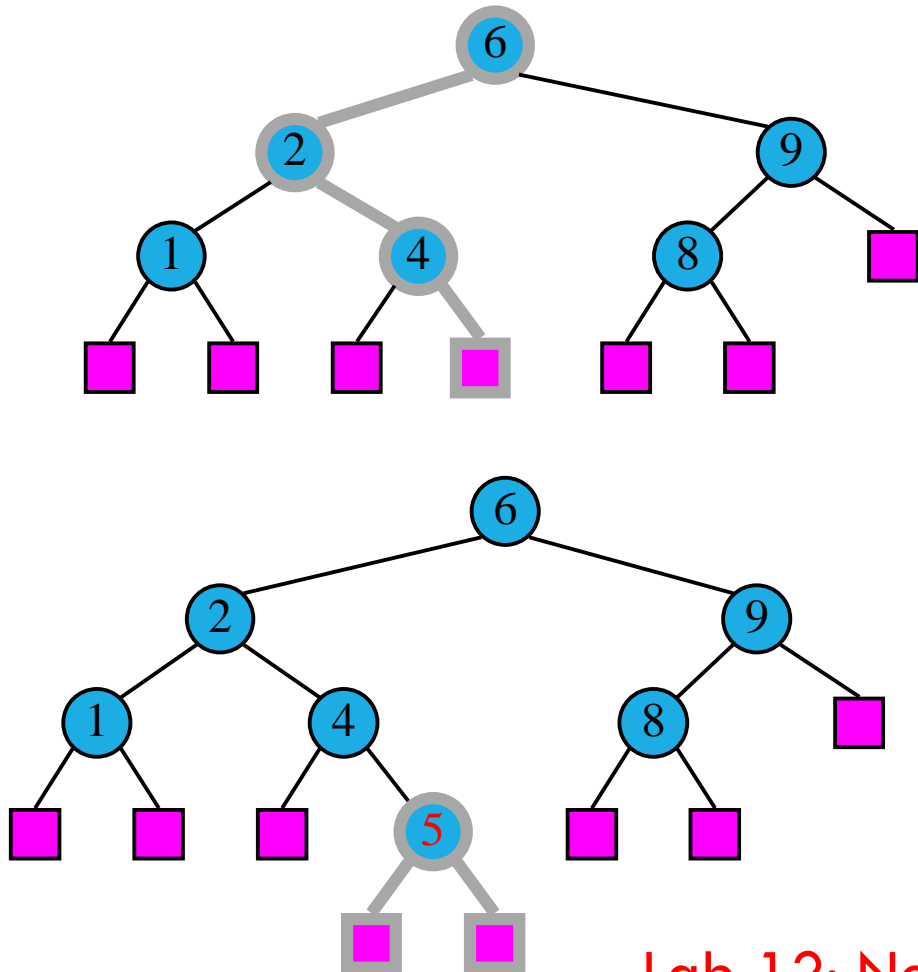
```
template <typename E>
typename SearchTree<E>::TPos
SearchTree<E>::finder(const K& k, const TPos& v) {
    if (v.isExternal()) return v; // Key not found
    if (k < (*v).key()) return finder(k, v.left());
    else if ((*v).key() < k) return finder(k, v.right());
    else return v;
}
```

```
template <typename E>
typename SearchTree<E>::Iterator
SearchTree<E>::find(const K& k) {
    TPos v = finder(k, root());
    if (v.isInternal()) {
        return Iterator(v); // Found it
    }
    else return end(); // Didn't find it
}
```

Lab 12: Next to next week's lab...



# INSERT INTO A BST



```
1  BST-Insert(T, z)
2    y := NIL
3    x := T.root
4    while x ≠ NIL do
5        y := x
6        if z.key < x.key then
7            x := x.left
8        else
9            x := x.right
10       end if
11    repeat
12    z.parent := y
13    if y = NIL then
14        T.root := z
15    else if z.key < y.key then
16        y.left := z
17    else
18        y.right := z
19    end if
```

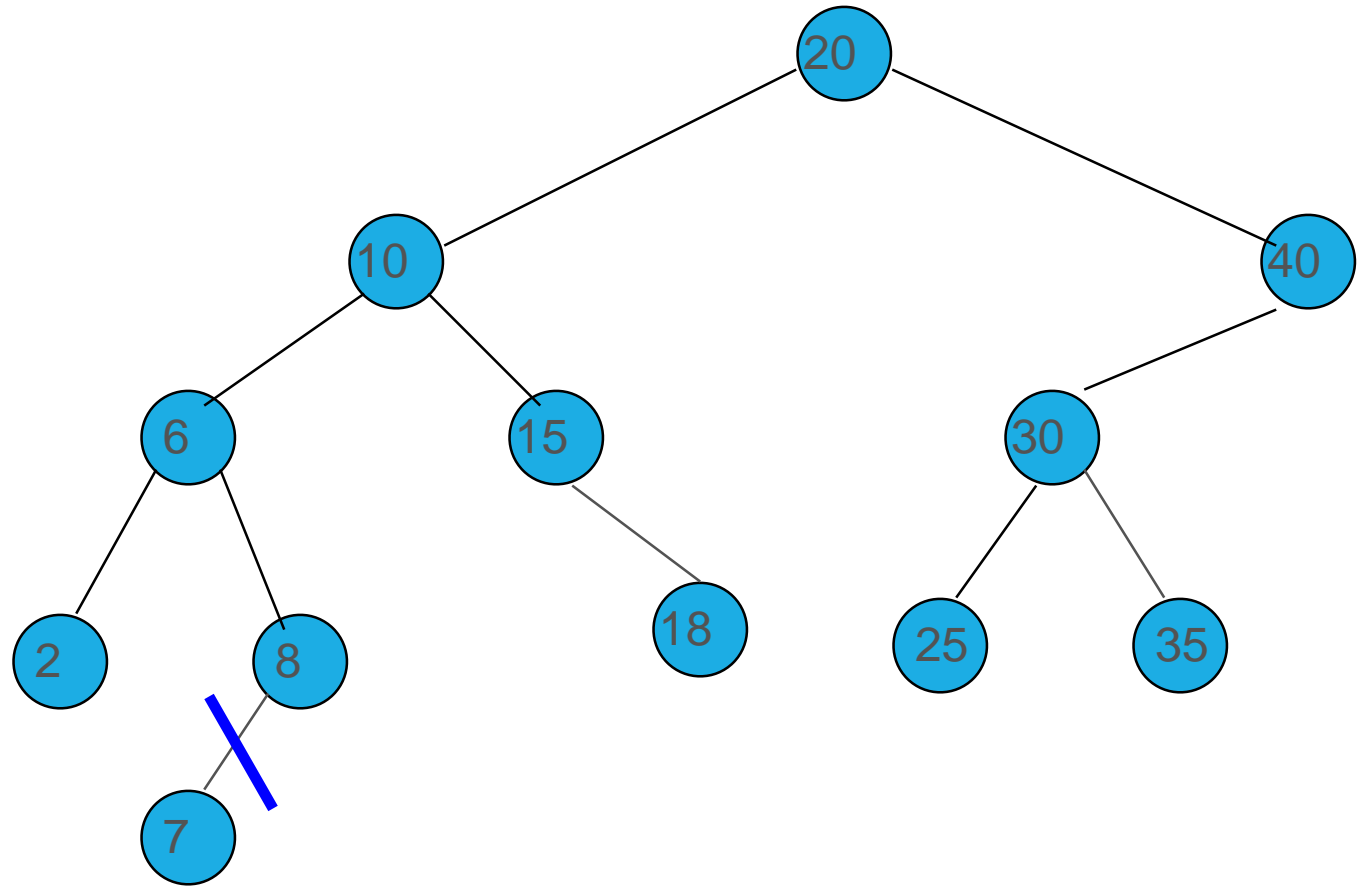
Lab 12: Next to next week's lab

Complexity?

# DELETE AN ITEM FROM BST

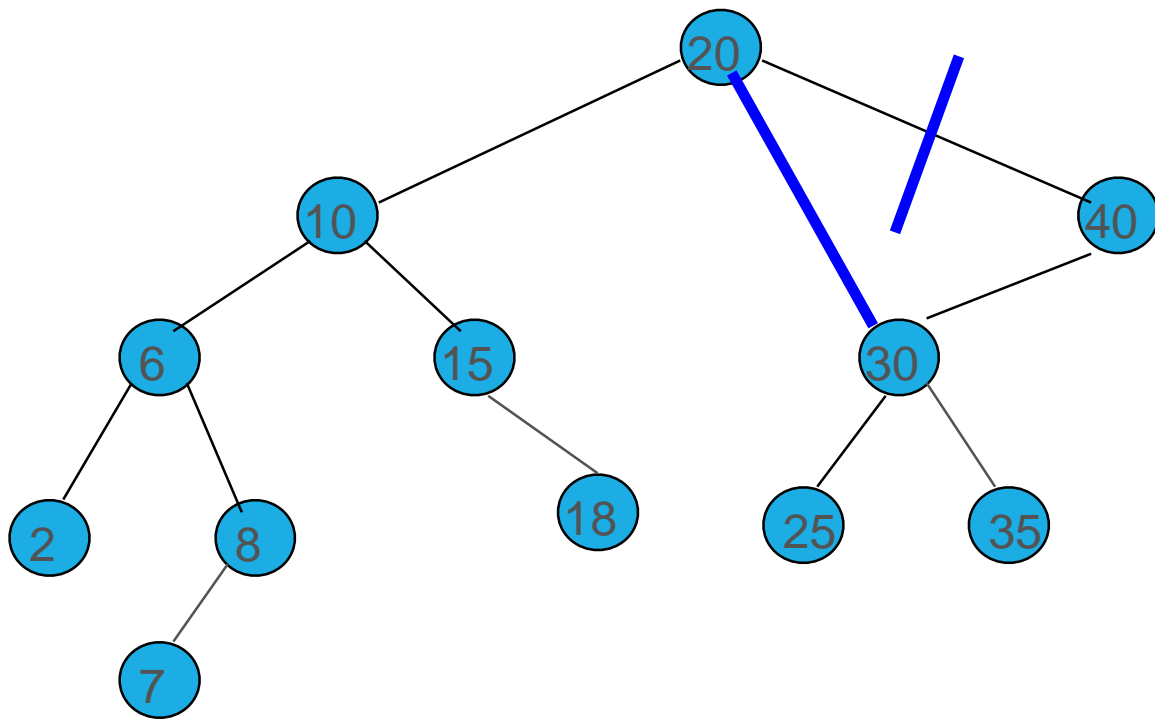
## Three cases:

- Element is in a leaf (Case I)
- Element is in a degree 1 node (Case II)
- Element is in a degree 2 node (Case III)

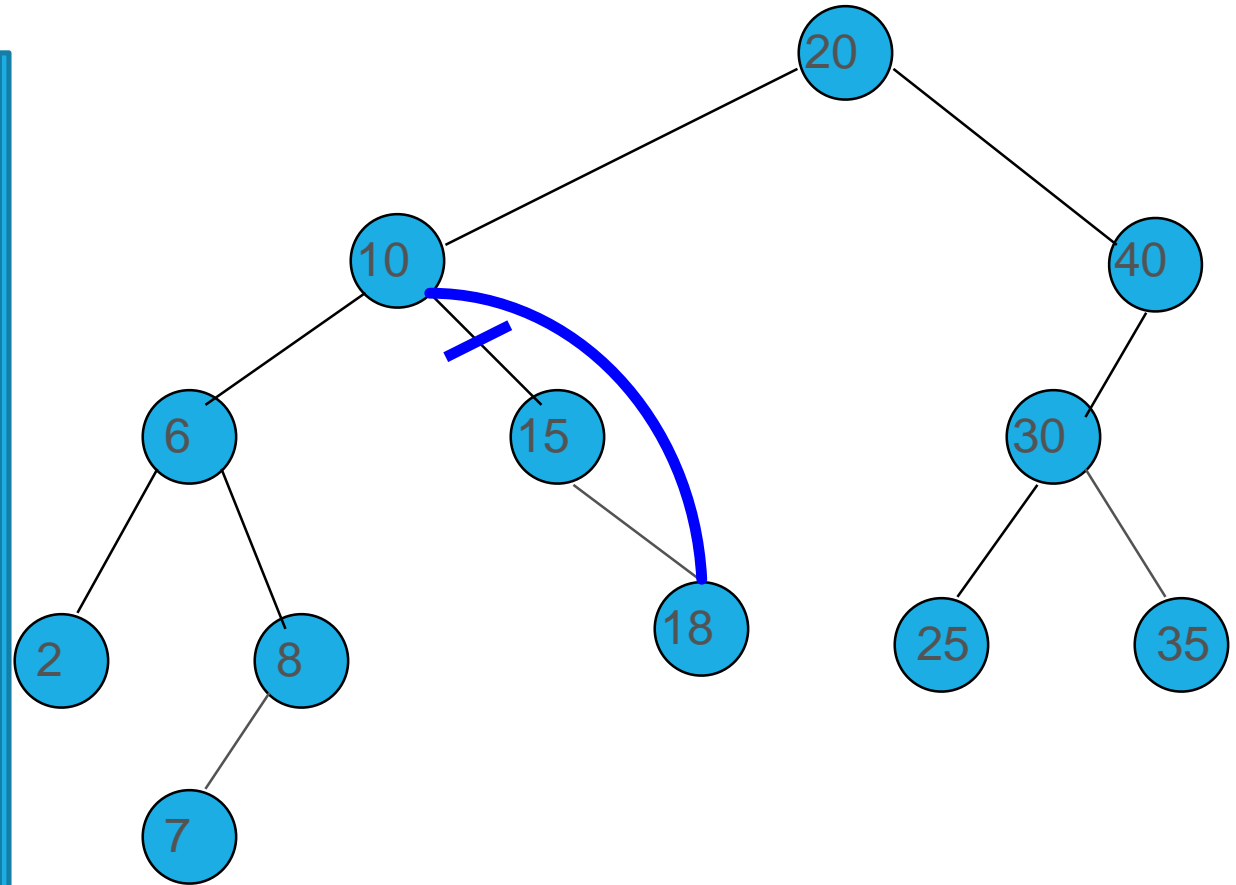


Case I: Erase key = 7

# CASE II

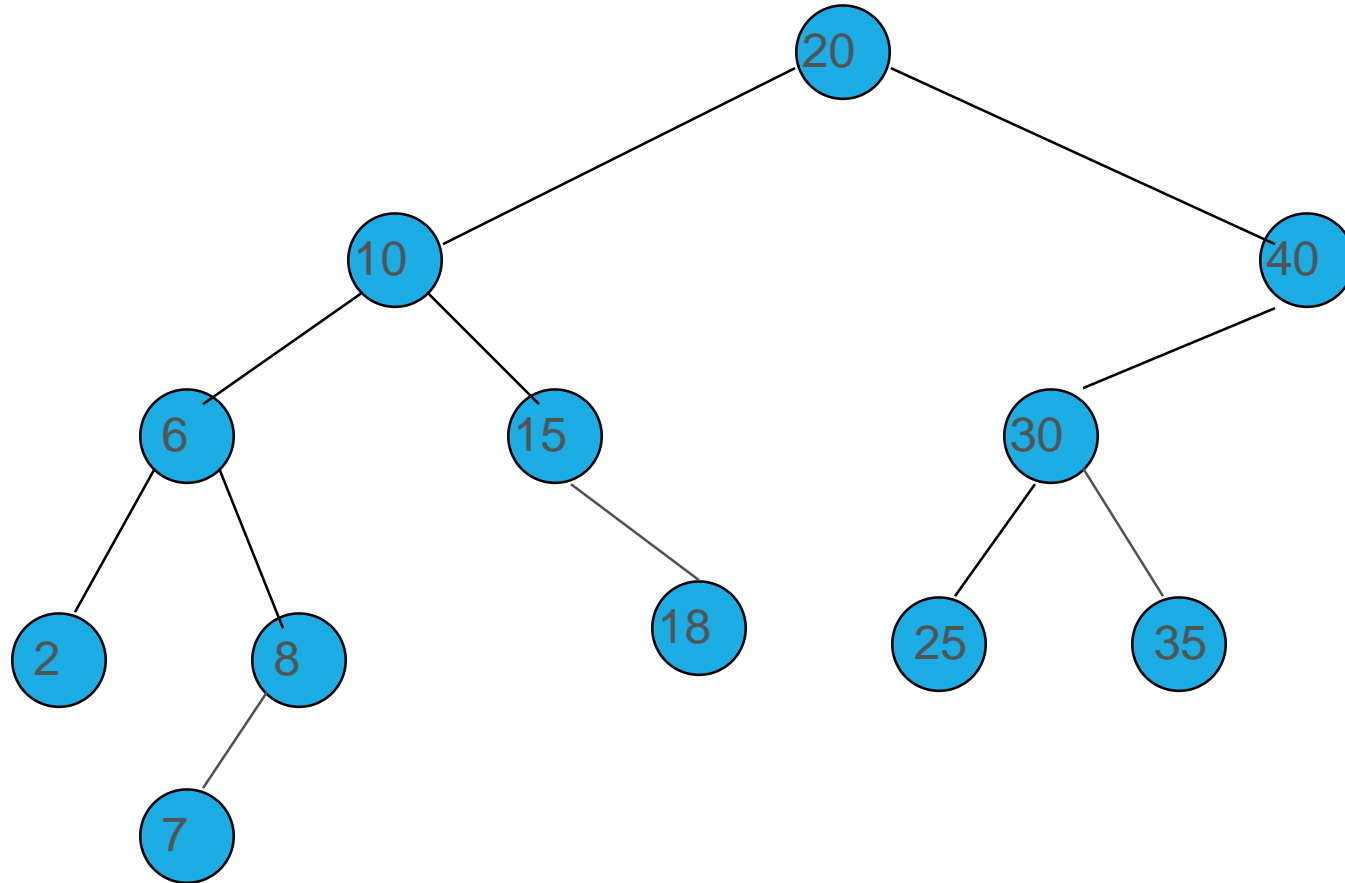


Erase key = 40



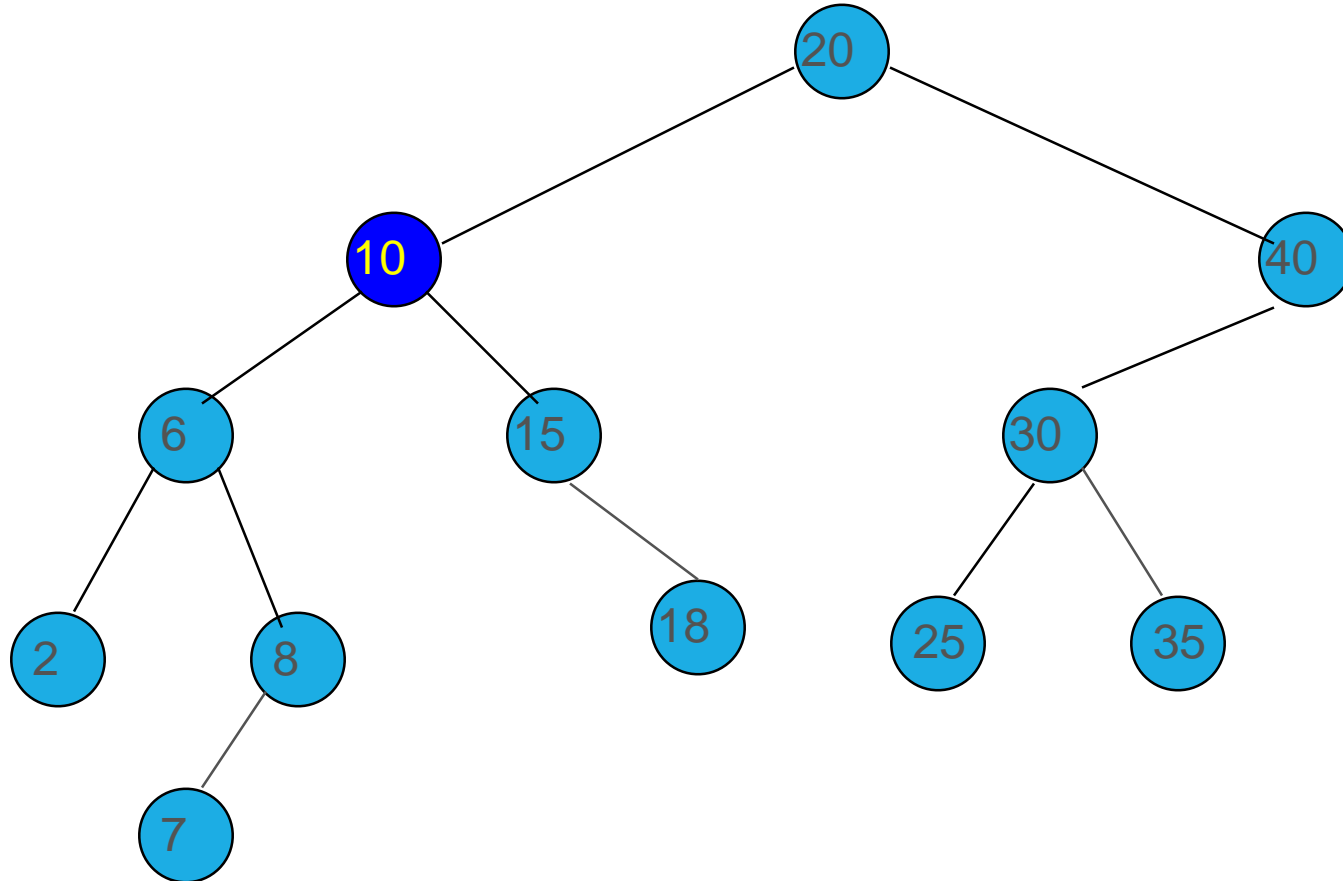
Erase key = 15

# CASE III



Erase from a degree 2 node. Erase key = 10

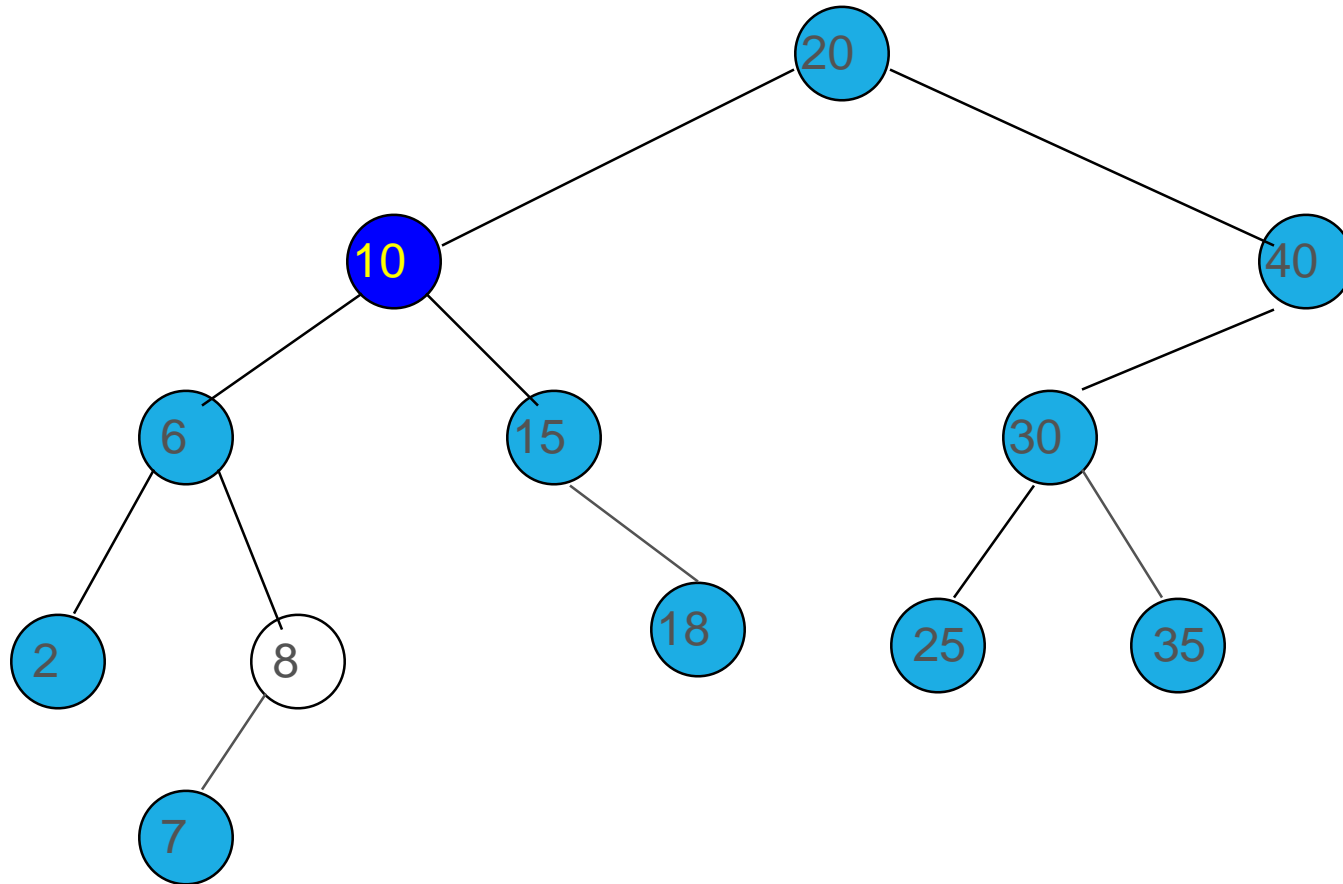
# CASE III CONTINUED...



Replace with largest key in left subtree (or smallest in right subtree).

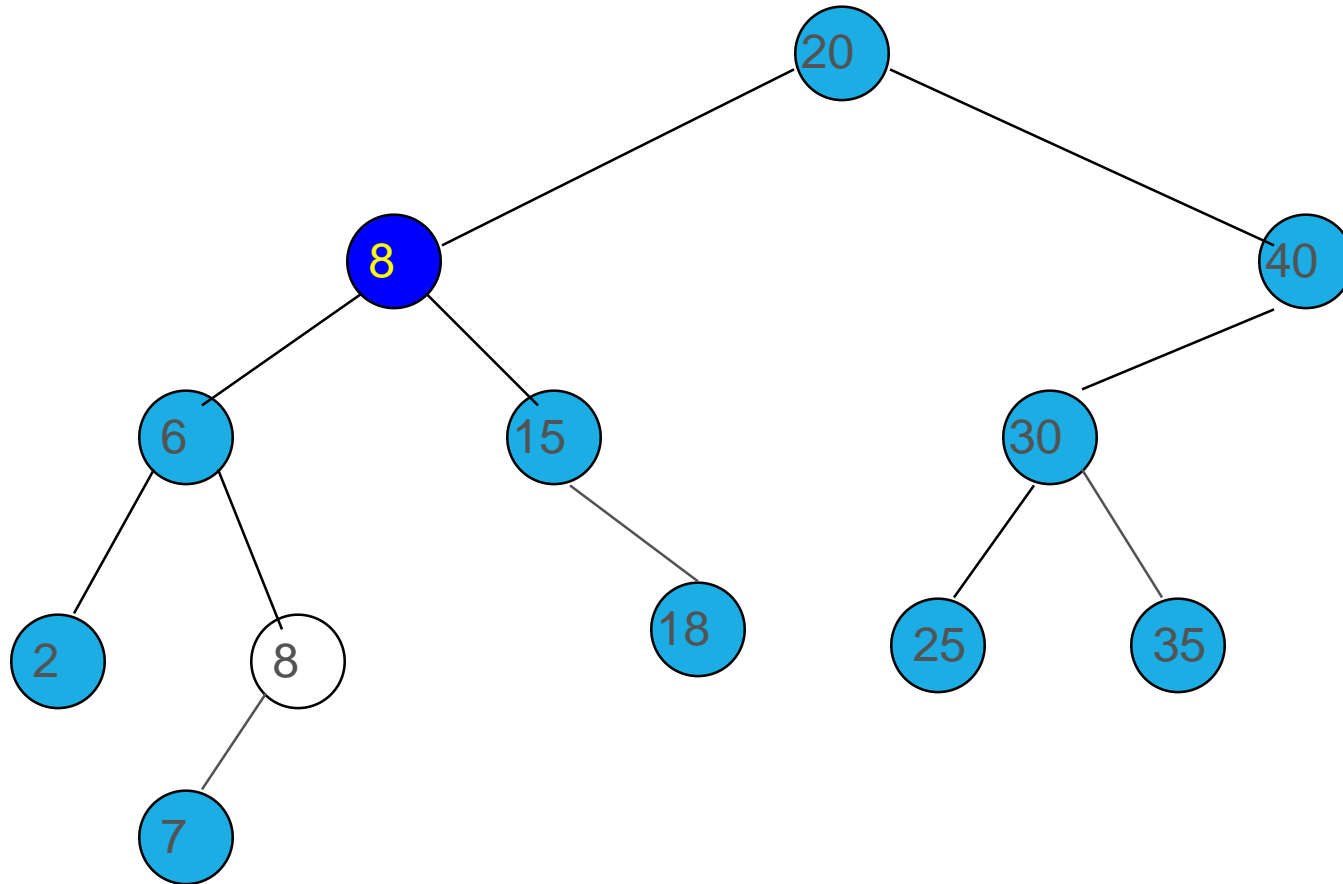


# CASE III CONTINUED...



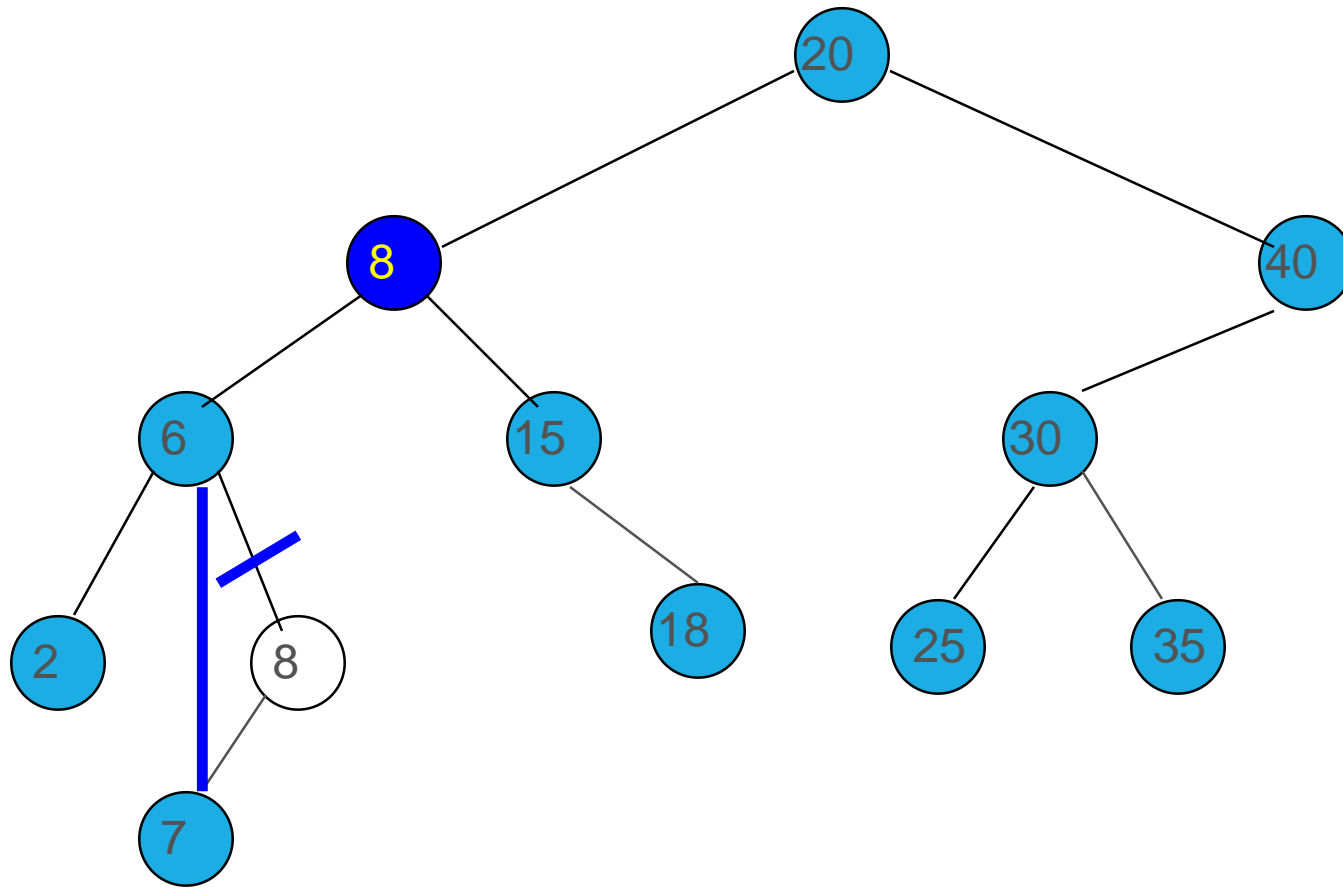
Replace with largest key in left subtree (or smallest in right subtree).

# CASE III CONTINUED...



Replace with largest key in left subtree (or smallest in right subtree).

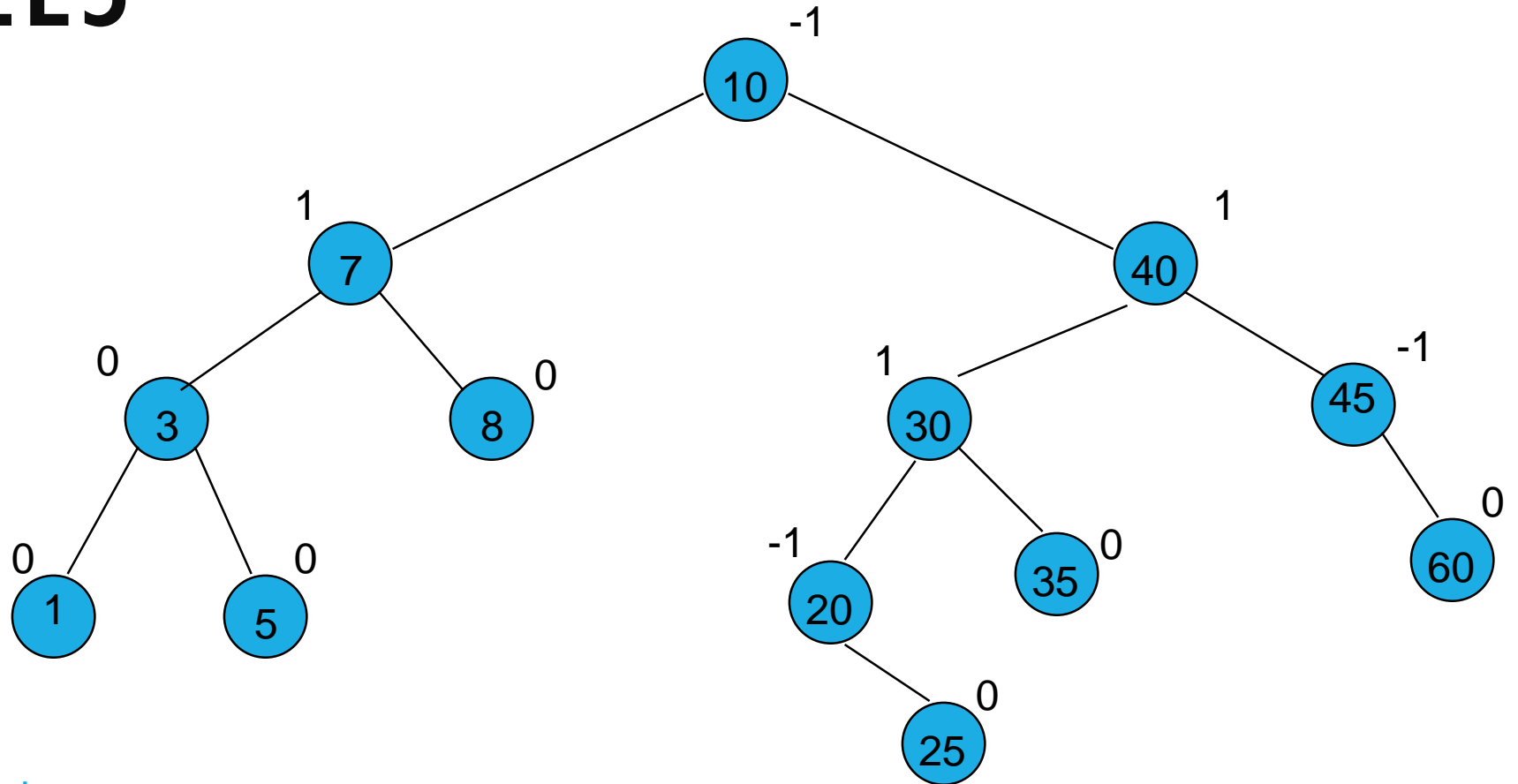
# CASE III CONTINUED...



Largest key must be in a leaf or degree 1 node.

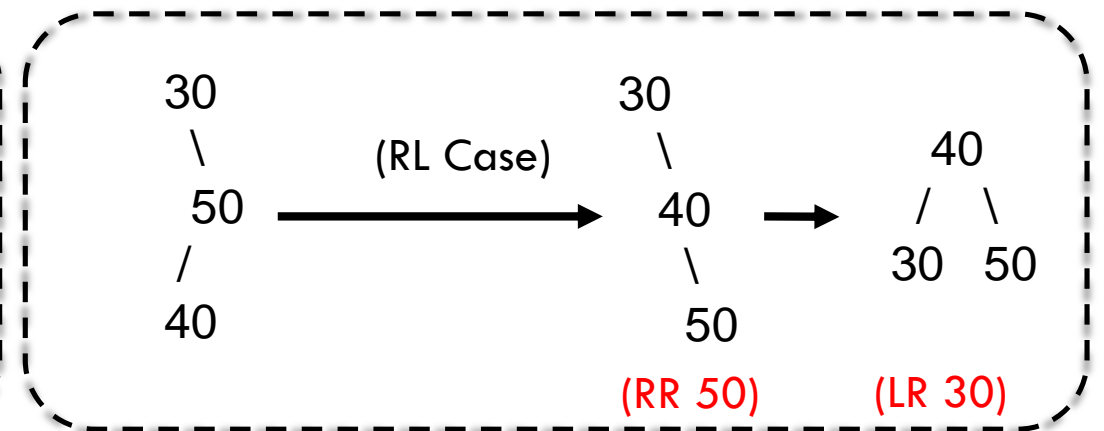
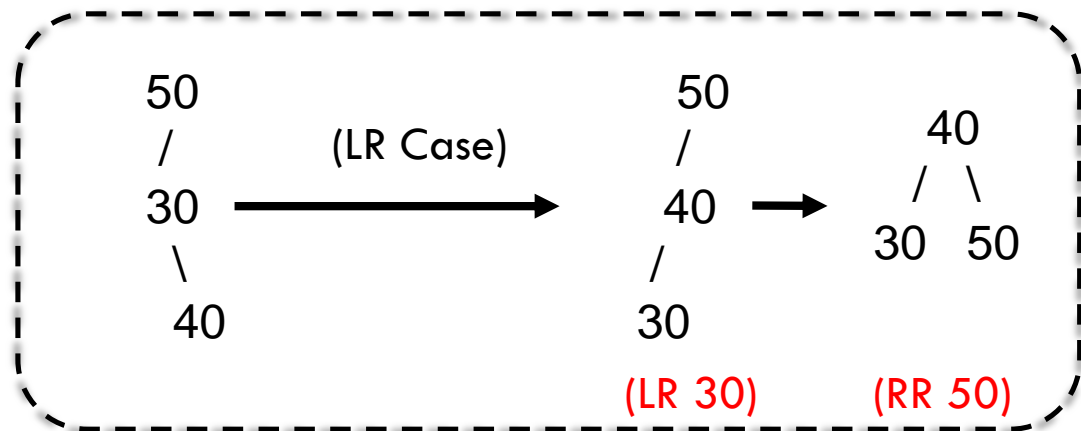
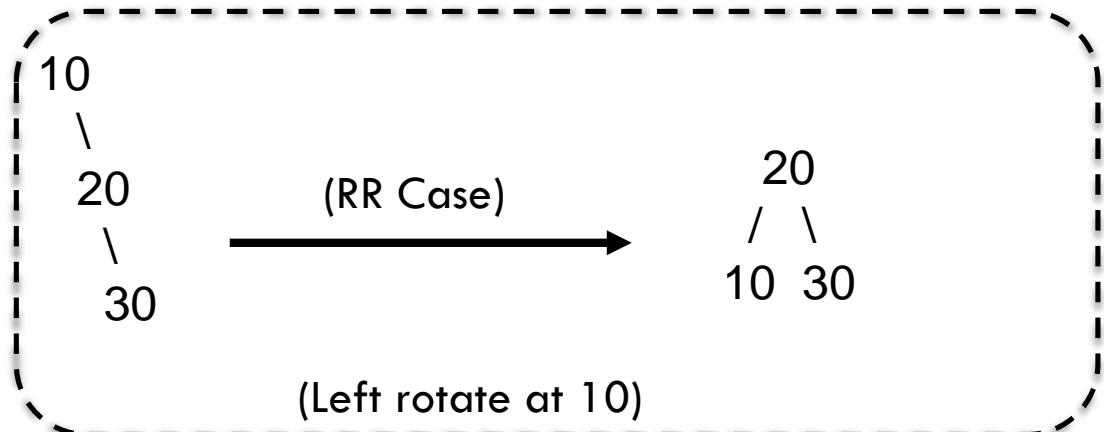
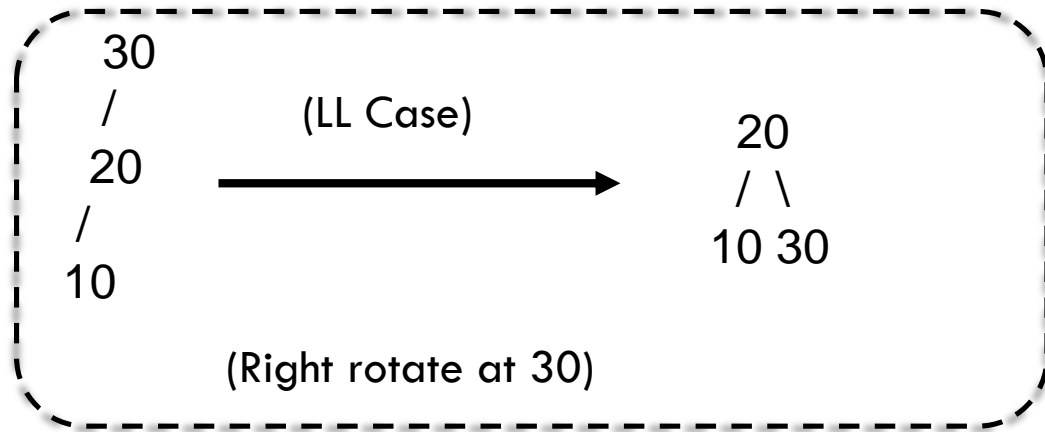
# AVL TREES

- Adelson-Velsky and Landis (Soviet mathematicians and computer scientists)

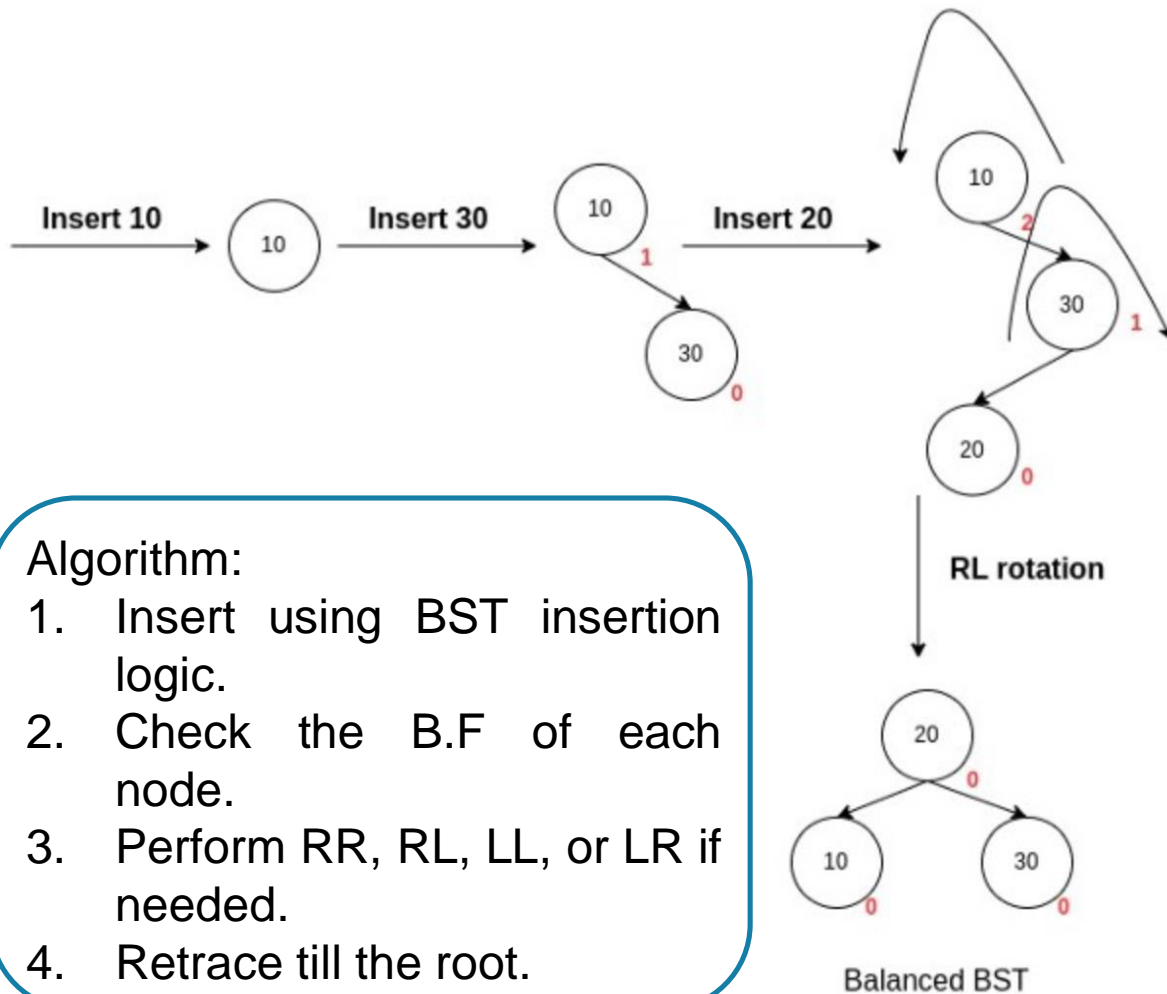


- BST with height-balance property.
- What happens to the Balance Factors and how will you handle the imbalance?

# BALANCING THE TREE THROUGH ROTATIONS

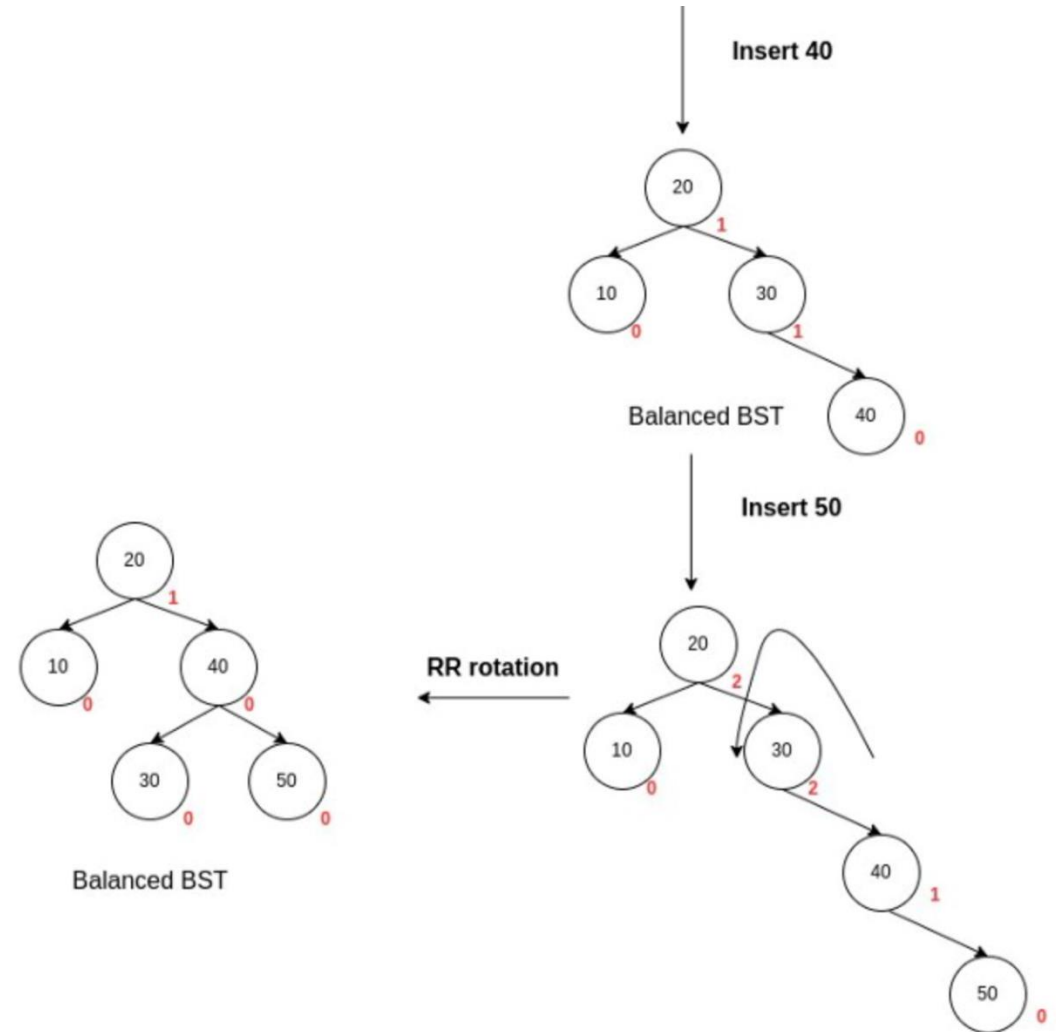


# ANOTHER EXAMPLE: ALL THE CASES



## Algorithm:

1. Insert using BST insertion logic.
2. Check the B.F of each node.
3. Perform RR, RL, LL, or LR if needed.
4. Retrace till the root.



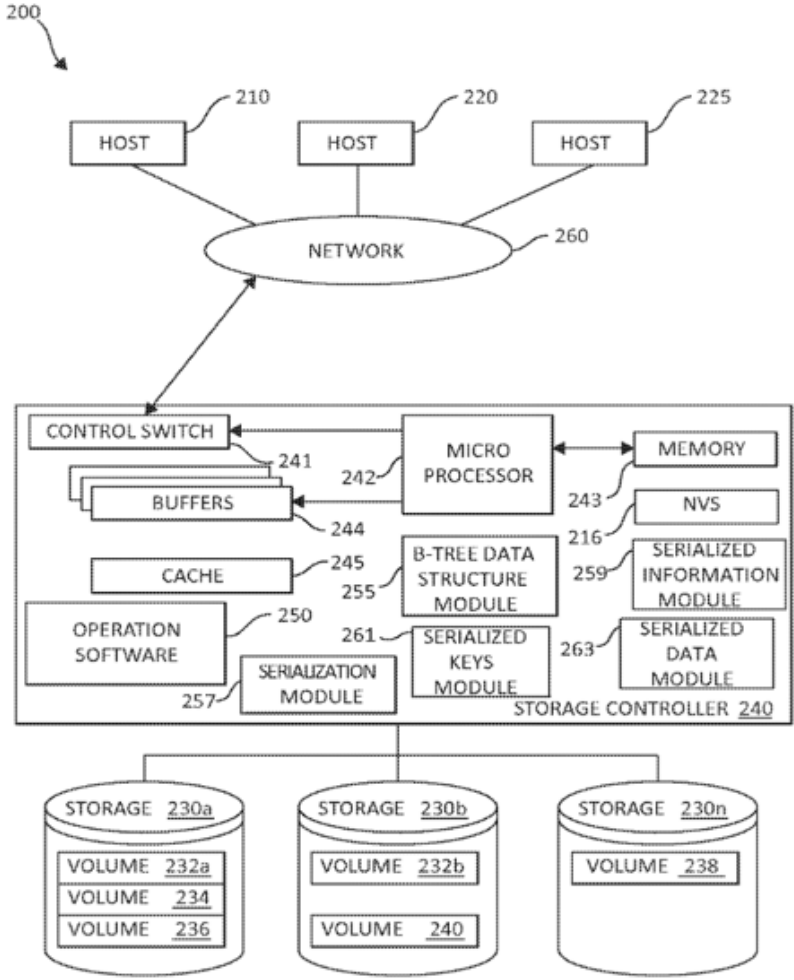
# C++ IMPLEMENTATION OF AVL TREE

```
110 template <typename K, typename V>
111 void Tree<K, V>::remove(const K& key, Node*& spot) {
112     if (spot == nullptr)
113         return;
114
115     if (spot->key < key)
116         remove(key, spot->right);
117
118     else if (spot->key > key)
119         remove(key, spot->left);
120
121     else if (spot->left != nullptr && spot->right != nullptr) {
122         spot->value = findMin(spot->right)->value;
123         remove(spot->value, spot->right);
124     }
125
126     else {
127         Node* oldNode = spot;
128         spot = (spot->left != nullptr) ? spot->right : spot->left;
129         delete oldNode;
130     }
131     balance(spot);
132 }
```

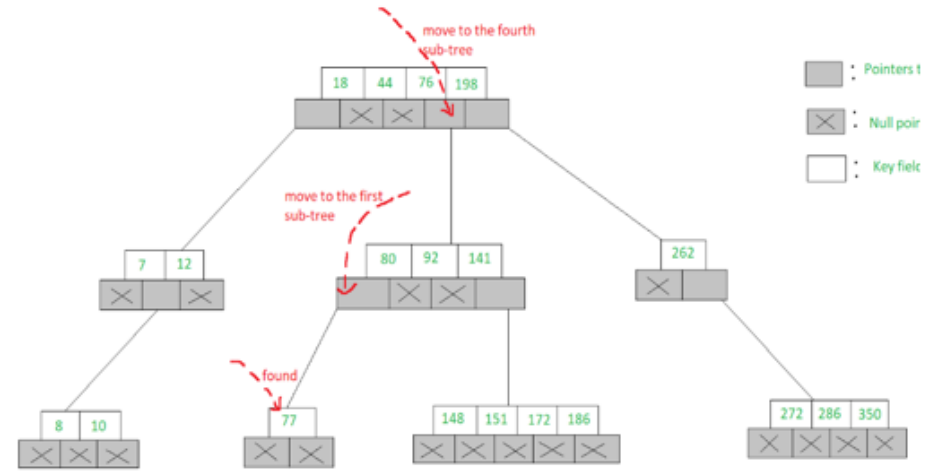
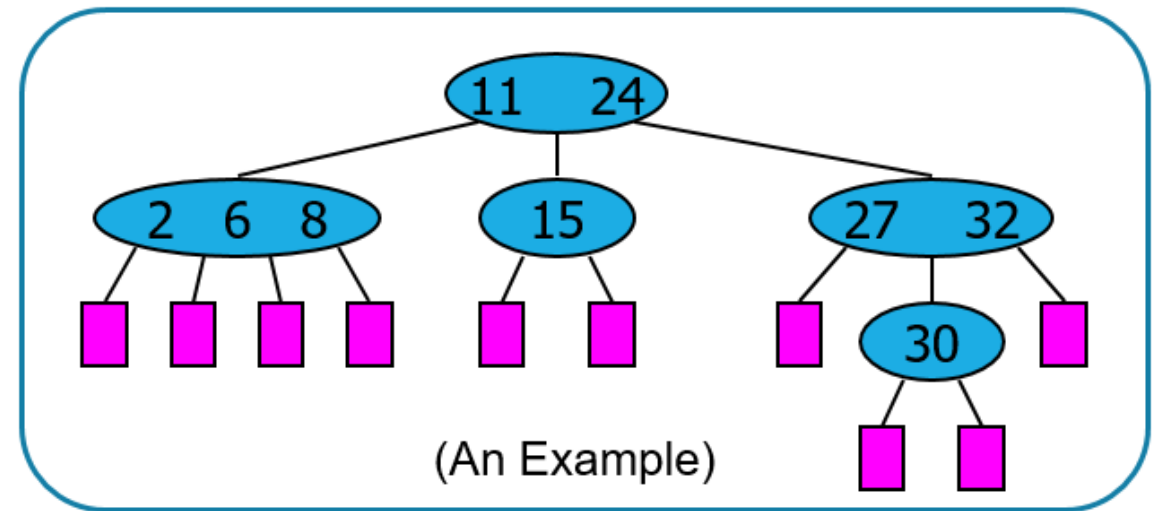
```
148 template <typename K, typename V>
149 void Tree<K, V>::balance(Node*& spot) {
150     if (spot != nullptr) {
151         //if violation is on left child
152         if (height(spot->left) - height(spot->right) > ALLOWED_IMBALANCE) {
153             //LL violation
154             if (height(spot->left->left) >= height(spot->left->right))
155                 rotateWithLeftChild(spot);
156             else //left-right violation
157                 doubleWithLeftChild(spot);
158         }
159         else {
160             //if violation is on right child
161             if (height(spot->right) - height(spot->left) > ALLOWED_IMBALANCE) {
162                 //RR violation
163                 if (height(spot->right->right) >= height(spot->right->left))
164                     rotateWithRightChild(spot);
165                 else //right-left violation
166                     doubleWithRightChild(spot);
167             }
168         }
169         spot->height = max(height(spot->left), height(spot->right)) + 1;
170     }
171 }
```

Lab 12: Next to next week...

# MULTI-WAY SEARCH TREE: ORDERED MAPS



<https://patents.google.com/patent/US9305040B2/en>



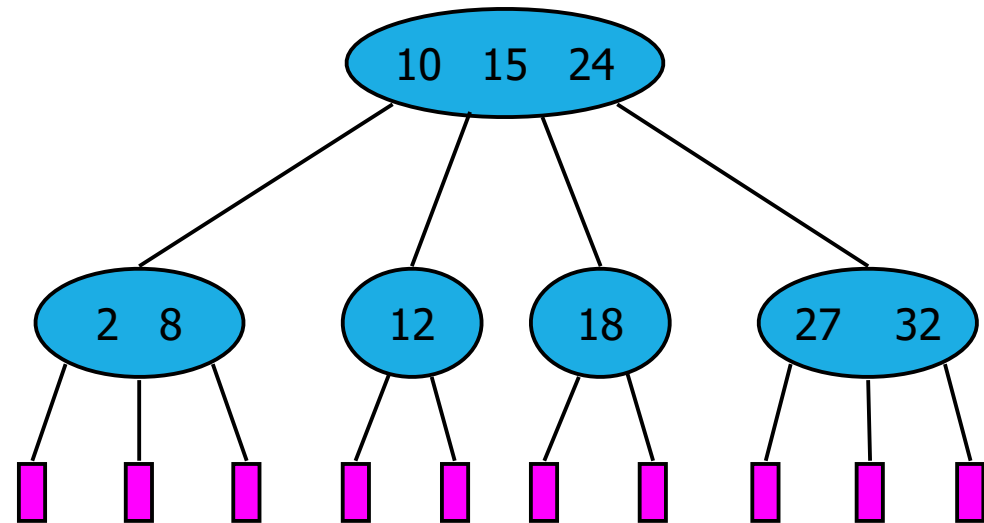


# (2,4) TREES

A (2,4) tree is a multi-way search tree with the following properties:

- Node-Size Property
- Depth Property

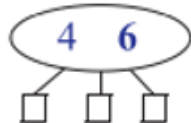
**Theorem:** A (2,4) tree storing  $n$  items has **height**  $O(\log n)$



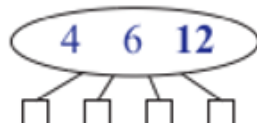
# INSERTION IN (2,4): **OVERFLOW** AND **SPLIT**



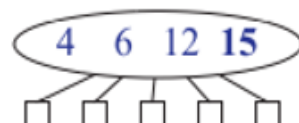
Insert 4



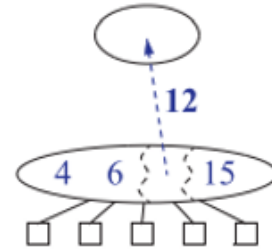
Insert 6



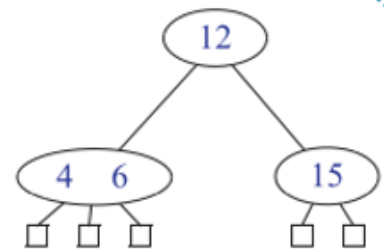
Insert 12



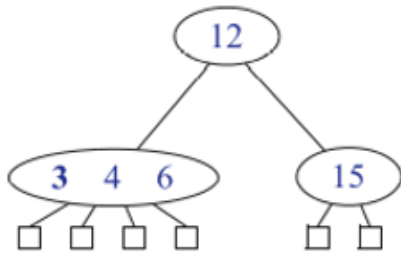
Insert 15



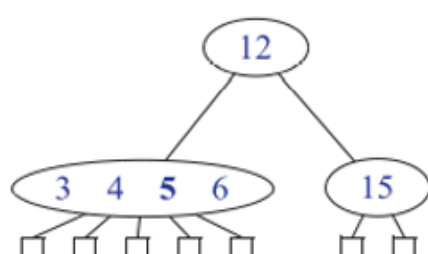
Split: creation of a new root node



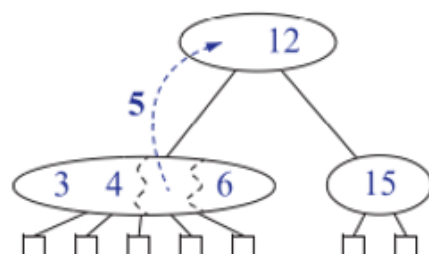
After the Split



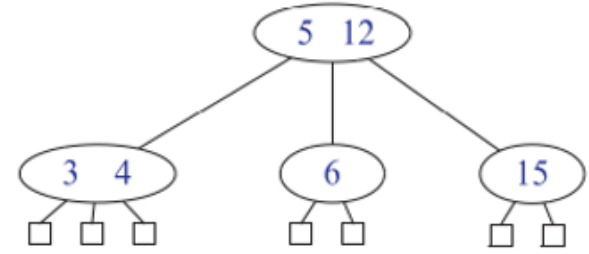
Insert 3



Insert 5

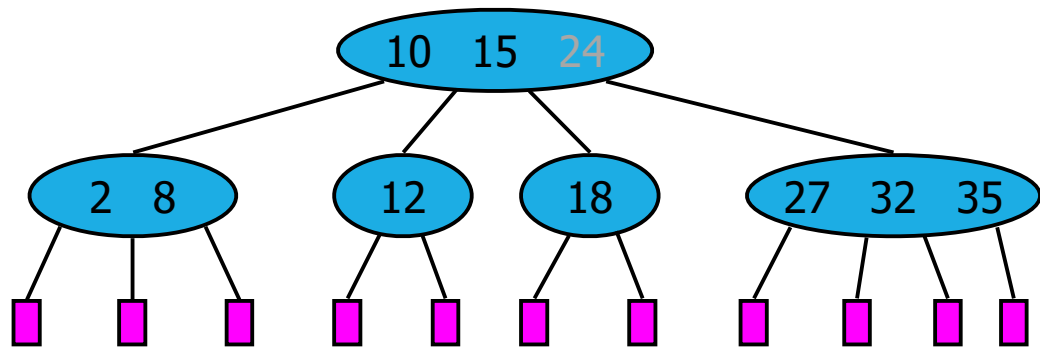


Overflow and split

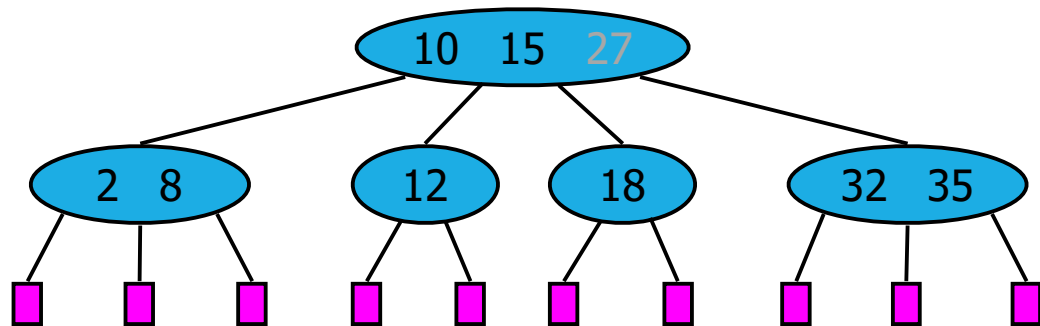


After the Split

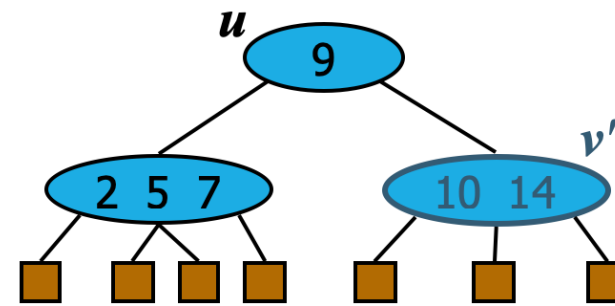
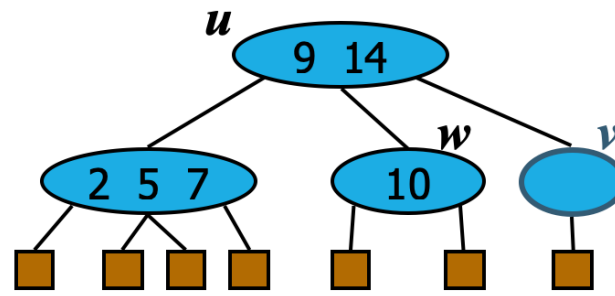
# DELETION IN (2,4): UNDERFLOW AND FUSION/TRANSFER



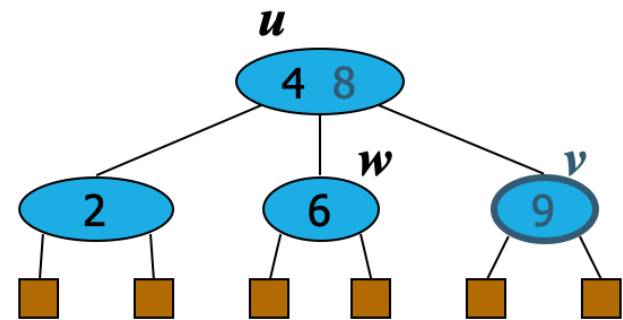
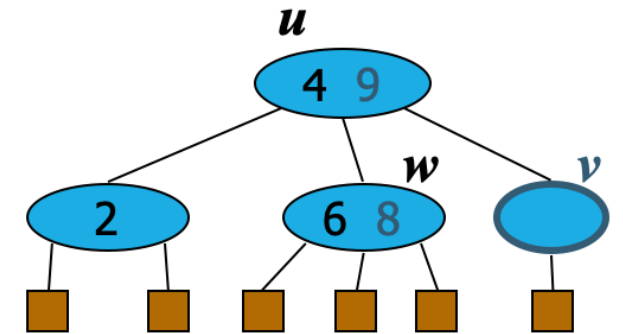
(deleting 24) ↓



(replace with *what?*)



(Case-I: underflow and fusion with 2-node sibling)



(Case-II: underflow and transfer with 3/4-node sibling)

# IMPL. OF 2-4 TREES

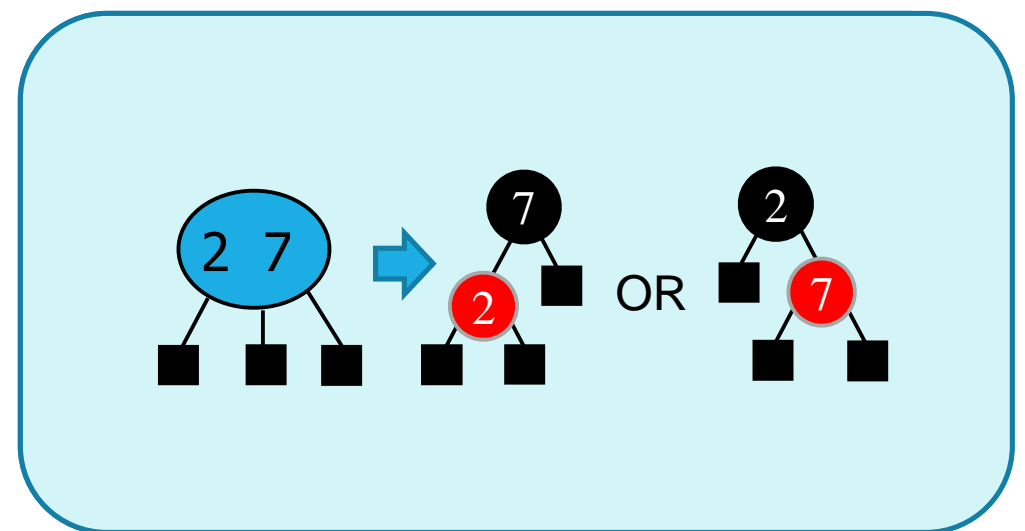
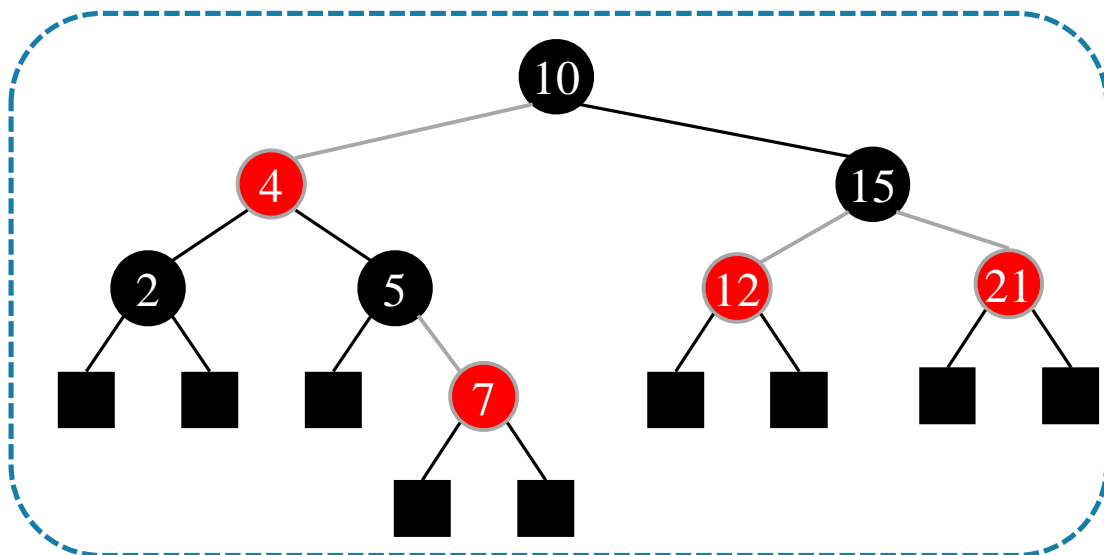
```
52 // Helper function to split a node into two nodes
53 void splitNode(TreeNode* node) {
54     int median = node->keys[1];
55
56     TreeNode* leftNode = new TreeNode(node->keys[0]);
57     TreeNode* rightNode = new TreeNode(node->keys[2]);
58
59     if (!node->children.empty()) {
60         leftNode->children.push_back(node->children[0]);
61         leftNode->children.push_back(node->children[1]);
62         rightNode->children.push_back(node->children[2]);
63         rightNode->children.push_back(node->children[3]);
64     }
65
66     node->keys.clear();
67     node->keys.push_back(median);
68     node->children.clear();
113 int main() {
114     Tree24 tree;
115     vector<int> keys={5, 9, 1, 3, 7, 6, 10, 8, 2, 4};
116
117     for (int key : keys) {
118         tree.insert(key);
119     }
```

```
In-order traversal: 1 2 3 4 5 6 7 8
Pre-order traversal: 3 1 2 6 4 5 7 8
Post-order traversal: 1 2 4 5 7 8 6 3
```

```
17 class Tree24 {
18 public:
19     TreeNode* root;
20
21     Tree24() {
22         root = nullptr;
23     }
24
25     // Insert a key into the 2-4 tree
26     void insert(int key) {
27         if (root == nullptr) {
28             root = new TreeNode(key);
29         } else {
30             insertKey(root, key);
31         }
32     }
33
34     // Helper function to insert a key into a node
35     void insertKey(TreeNode* node, int key) {
36         int i = node->keys.size() - 1;
37         if (node->children.empty()) {
38             node->keys.push_back(key);
39             sort(node->keys.begin(), node->keys.end());
40         } else {
41             while (i >= 0 && key < node->keys[i]) {
42                 i--;
43             }
44             insertKey(node->children[i + 1], key);
45         }
46
47         if (node->keys.size() == 4) {
48             splitNode(node);
49         }
50     }
```

# RED-BLACK TREE (RBT): AN ALTERNATIVE TO (2,4)

- Can we do away with complex **Rotations** (AVL tree) or **Split/Fusion** operations (2-4 trees)?
- **Red-Black** trees are self balancing Binary Search Trees (BSTs)
- Same logarithmic time performance  $O(\log n)$  like AVL and (2,4)
- But, **simpler implementation** with a single node type that can be colored **red** or black
- Simulate (2-4) trees in a Binary tree (BST)



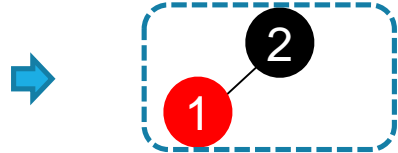
# INSERTING INTO RBT: HANDLING DOUBLE RED

## Example 1:

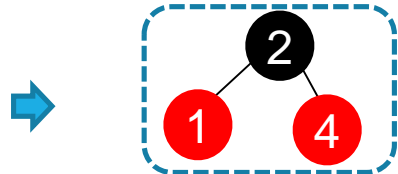
Insert 2



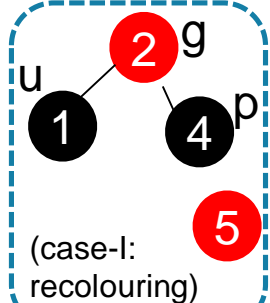
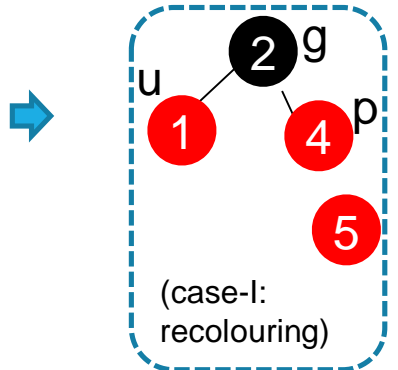
Insert 1



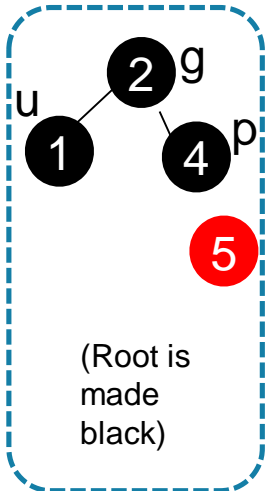
Insert 4



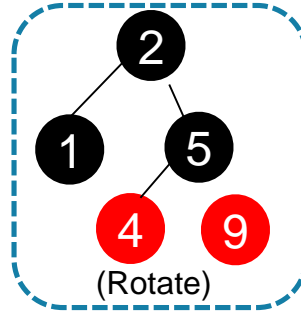
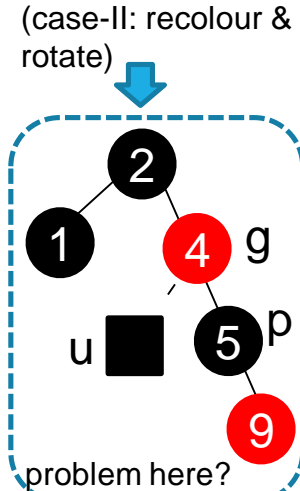
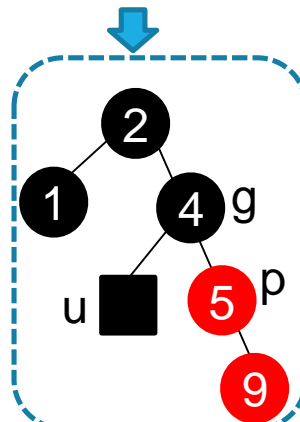
Insert 5



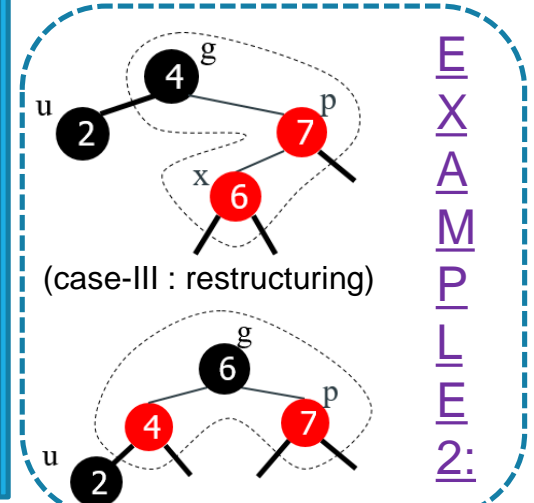
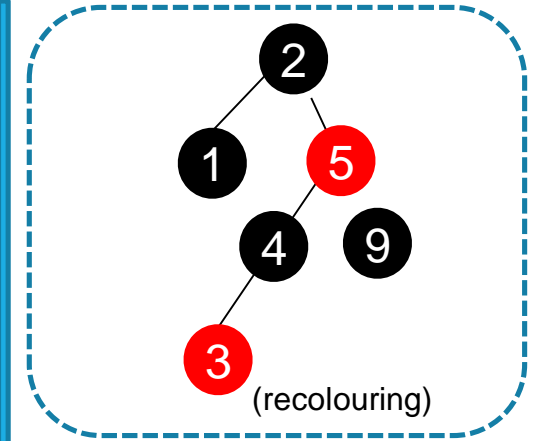
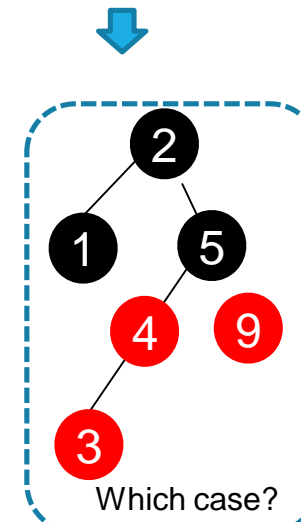
What should we do now?



Insert 9



Insert 3

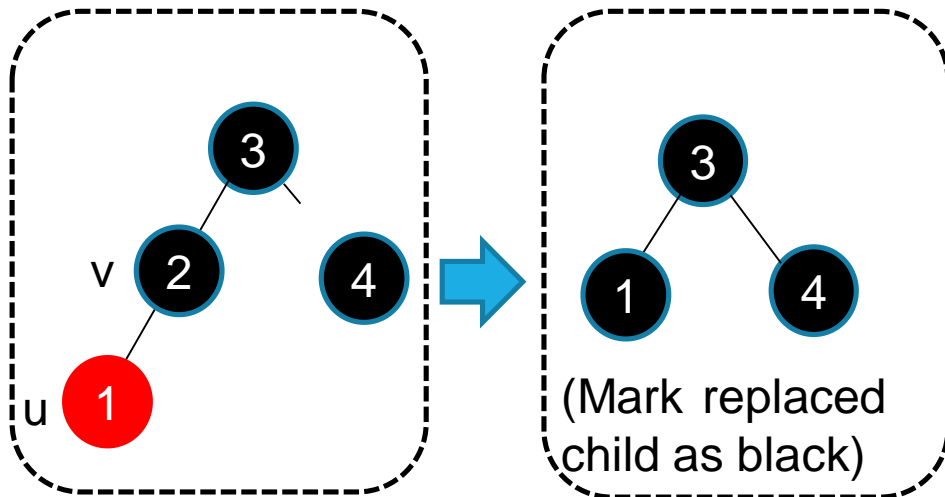


EXAMPLE 2:

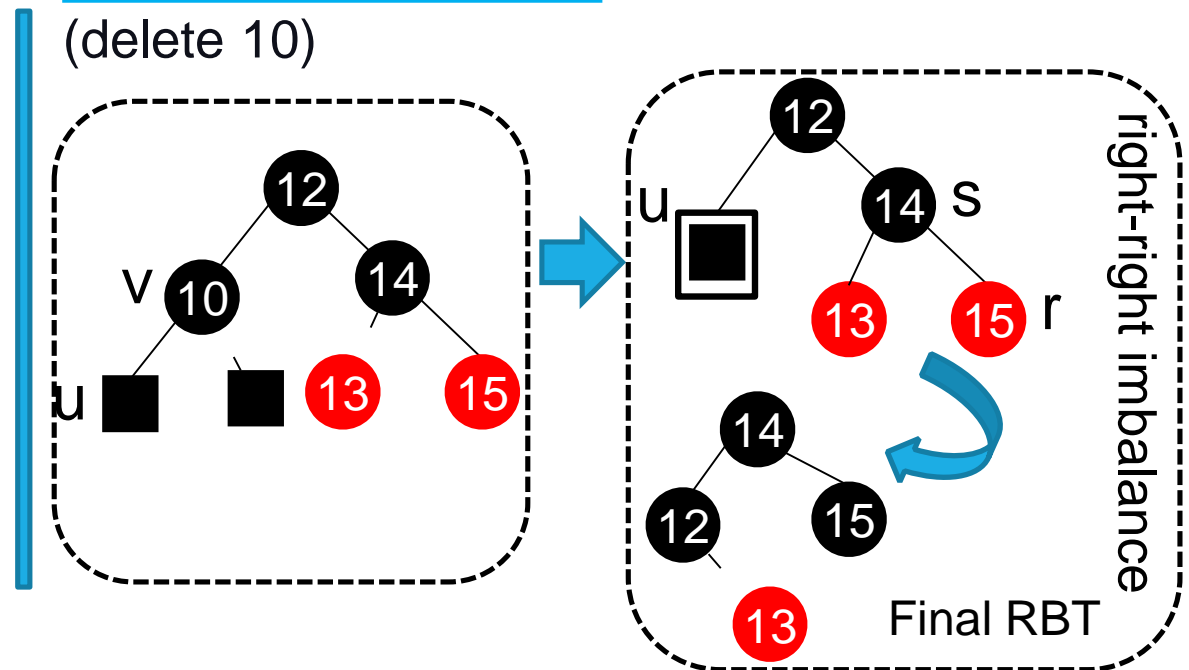
# DELETION IN A RED BLACK TREE

- Similar to BST, except that after deletion check if all the properties of RBT are satisfied.
- If not, perform recolor or rotation followed by recoloring to make it balanced.

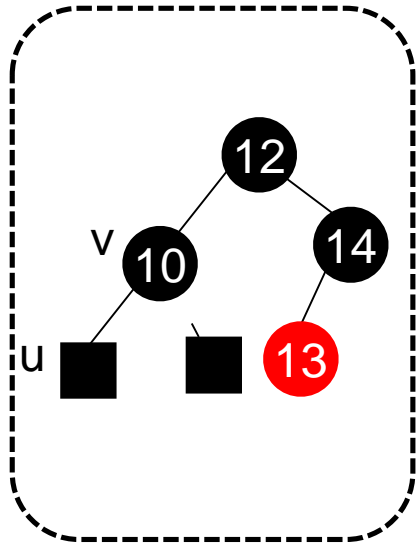
Case-I: If either v or u is red (delete 2)



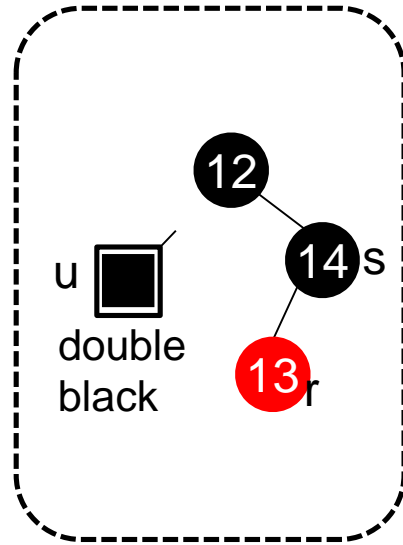
Case-II: Double black: If both v and u are black (delete 10)



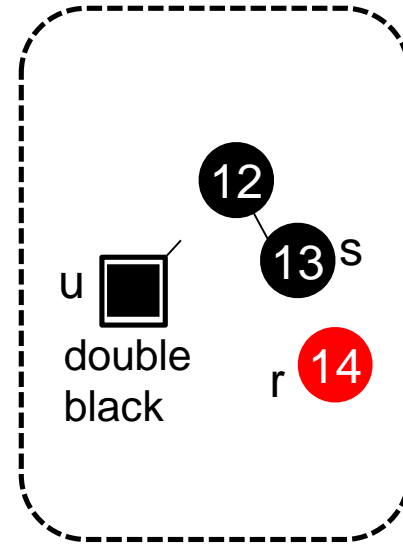
# CASE-II CONTINUED...



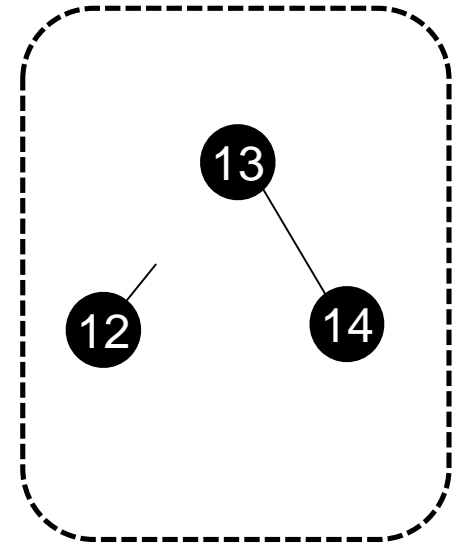
delete 10



right left imbalance



right rotation & recolouring



left rotation & recolouring



# C++ IMPLEMENTATION OF RBT

```
1 : Insert
2 : Find
3 : Erase
4 : Exit
Enter option : 1
Enter key and value : 10 Ramesh
Enter option : 1
Enter key and value : 20 Suresh
Enter option : 1
Enter key and value : 30 Radha
Enter option : 1
Enter key and value : 40 Shyam
Enter option : 2
Enter key to find : 30
Radha
Enter option : 3
Enter key to erase : 40
Enter option : 2
Enter key to find : 40
Key Not found
Enter option : █
```

```
119 void insert_case3(Node * inserted, Node * & root) {
120     // parent and uncle are red, flip colors
121     Node * my_uncle = uncle(inserted), * my_grandparent = grandparent(inserted);
122     if(!my_uncle || !my_grandparent) return;
123     // if there is no uncle or grandparent don't do anything
124     if(is_red(my_uncle)) {
125         inserted->parent->red = false;
126         my_uncle->red = false;
127         my_grandparent->red = true;
128         insert_case1(my_grandparent, root);
129     } else {
130         insert_case4(inserted, root);
131     }
132 }
185 void delete_case2(Node * removed, Node * & root) {
186     // node and brother are red, flip colors, make them black and parent red
187     Node * my_brother = brother(removed);
188     if(!my_brother) return;
189     if(is_red(my_brother)) {
190         removed->parent->red = true;
191         my_brother->red = false;
192         if(removed == removed->parent->left) rotate_with_right_child(removed->parent, root);
193         else rotate_with_left_child(removed->parent, root);
194     }
195     delete_case3(removed, root);
196 }
```



**THANK YOU!**

Next class: Dividing and Conquer, ...